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## E theory in seven dimensions

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### *Abstract*

We construct the non-linear realisation of the semi-direct product of  $E_{11}$  and its vector representation in its decomposition into the subalgebra  $GL(7) \otimes SL(5)$  to find a seven dimensional theory. The resulting equations of motion essentially follow from the Dynkin diagram of  $E_{11}$  and if one restricts them to contain only the usual fields of supergravity and the derivatives with respect to the usual coordinates of spacetime then these are the equations of motion of seven dimensional supergravity.

## 1 Introduction

It has been conjectured [1, 2] that the low energy effective action of strings and branes is the non-linear realisation of  $E_{11} \otimes_s l_1$ , where  $\otimes_s$  is the semi-direct product and  $l_1$  is the vector representation. The fields of the theory arise out of the  $E_{11}$  algebra, and the generalised space-time that the fields depend on is appears due to the  $l_1$  representation. The different maximal supergravity theories appear when one takes different decompositions of  $E_{11}$  [3,4,5,6]. For each decomposition the fields and coordinates are classified according to a level and the low level fields are those of the corresponding maximal supergravity and the level zero coordinates are the usual coordinates of spacetime. The equations of motion follow from the symmetries of the non-linear realisation and it was clear from early on that the  $E_{11} \otimes_s l_1$  non-linear realisation might contain all the maximal supergravities in a single theory. Although the early  $E_{11}$  papers contain part of the equations of motion in various dimensions it was only in references [7,8] that the equations of motion were found for the eleven and five dimensional theories. When these equations, which essentially followed uniquely from the non-linear realisation, were truncated to contain only the fields that are associated with the supergravity theories and the only coordinates is the usual coordinates of spacetime, then the equations are precisely with those of the eleven and five dimensional supergravity theories. For a review of E theory see reference [9].

In this paper we will carry out the decomposition of the  $E_{11} \otimes_s l_1$  algebra into  $GL(7) \otimes GL(5)$  to find the seven dimensional theory and then construct the corresponding non-linear realisation and so the equations of motion in seven dimensions. In more detail in section 2, we derive the decomposition of  $E_{11} \otimes l_1$  corresponding to the seven dimensional theory and then use these results to construct the Cartan forms in section 3. Section 4 focuses on finding the transformations of the Cartan forms and in section 5 we derive the equations of motion of seven dimensional theory.

We first recall the non-linear realisation, specifically with respect to the algebra we are interested in, namely,  $E_{11} \otimes_s l_1$ . This has been discussed in previous papers, but we will briefly repeat it here for convenience. We construct the non-linear realisation using the group element  $g \in E_{11} \otimes_s l_1$  with

$$g = g_l g_E , \quad (1.1)$$

where  $g_l$  is the group element made of generators of the  $l_1$  representation of the  $E_{11}$  algebra, and  $g_E$  is a group element of  $E_{11}$ . In terms of the generators, these group elements can be written as

$$g_l = e^{z^A l_A} , \quad g_E = e^{A_{\underline{\alpha}} R^{\underline{\alpha}}} . \quad (1.2)$$

where  $R^{\underline{\alpha}}$  are the generators of the  $E_{11}$  algebra and  $l_A$  are the generators of the vector representation of  $E_{11}$ . The  $A_{\underline{\alpha}}$  will turn out to be the fields of our theory, and the  $z^A$  are the generalised space-time coordinates upon which the fields will depend.

The non-linear realisation is invariant under transformations

$$g \rightarrow g_0 g , \quad g_0 \in E_{11} \otimes_s l_1 , \quad (1.3)$$

$$g \rightarrow gh , \quad g \in I_c(E_{11}) . \quad (1.4)$$

where  $g_0 \in E_{11}$  is a rigid transformation, and  $h$  is an element of the Cartan involution invariant subalgebra  $I_c(E_{11})$ , and is a local transformation. The Cartan involution acts on a generator of  $E_{11}$  as  $I_c(R^\alpha) = -R^{-\alpha}$  for a root  $\alpha$ , and hence the Cartan involution invariant subalgebra is generated by  $R^\alpha - R^{-\alpha}$ .

The dynamics of the non-linear realisation are a set of equations of motion which is invariant under the transformations in equation (1.3)-(1.4). We will construct the invariant dynamical equations from the Cartan forms which are given by

$$\mathcal{V} = g^{-1}dg = \mathcal{V}_E + \mathcal{V}_l, \quad (1.5)$$

which we have split into terms containing the  $E_{11}$  generators and terms containing the  $l_1$  representation, explicitly

$$\mathcal{V}_E = g_E^{-1}dg_E = dz^\Pi G_{\Pi,\underline{\alpha}} R^\alpha, \quad (1.6)$$

$$\mathcal{V}_l = g_l^{-1}dg_l = g_E^{-1}(g_l^{-1}dg_l)g_E = dz^\Pi E_\Pi^A l_A, \quad (1.7)$$

where  $G_{\Pi,\underline{\alpha}}$  are the Cartan forms of  $E_{11}$  and  $E_\Pi^A = (e^{A\underline{\alpha}D^\alpha})_\Pi^A$  is the vielbein on the generalised spacetime.

Both  $\mathcal{V}_E$  and  $\mathcal{V}_l$  are invariant under the rigid transformations, but transform in the following way under the local transformations

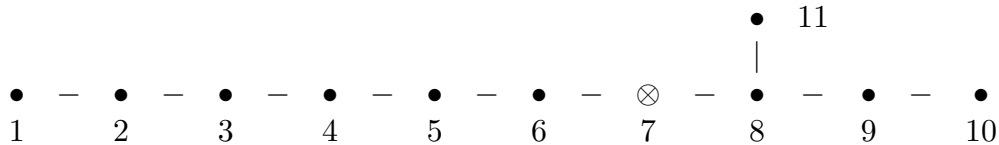
$$\mathcal{V}_E \rightarrow h^{-1}\mathcal{V}_E h + h^{-1}dh, \quad \mathcal{V}_l \rightarrow h^{-1}\mathcal{V}_l h. \quad (1.8)$$

## 2 The $E_{11}$ algebra in seven dimensions

We begin by giving the algebra of  $E_{11}$  in 7 dimensions. The algebra of the positive root generators was given in the paper of reference [10]. In this paper we will extend these to the full  $E_{11}$  algebra and so include the negative root generators. We will also construct the commutators of the  $E_{11}$  generators with those of the  $l_1$  representation. Furthermore, we will construct the Cartan involution invariant subalgebra, denoted by  $I_c(E_{11})$  algebra.

### 2.1 The $E_{11}$ algebra in seven dimensions

To find the seven dimensional theory we delete node seven in the  $E_{11}$  Dynkin diagram, whereupon we find the algebra  $SL(7) \otimes SL(5)$ . The Dynkin diagram is



The cross on node 7 represents the fact that this is the deleted node. Decomposing the  $E_{11}$  algebra into representations of this algebra the generators of level zero and above are given by [10]

$$K^a{}_b, \quad R^M{}_N; \quad R^{aMN}; \quad R^{a_1 a_2}{}_M; \quad R^{a_1 a_2 a_3}{}_M; \quad R^{a_1 \dots a_4}{}_{MN}; \quad R^{a_1 \dots a_5}{}_N,$$

$$R^{a_1 \dots a_4, b}; \quad R^{a_1 \dots a_6}_{MN, P}, \quad R^{a_1 \dots a_6 (MN)}, \quad R^{a_1 \dots a_5, b MN}, \dots \quad (2.1.1)$$

The indices with the round brackets surrounding them are symmetric in their permutation. The indices in the remaining blocks are totally antisymmetric (where a comma indicates a new antisymmetric block), and they belong to irreducible representations of  $SL(7) \otimes SL(5)$  and so

$$\sum_N R^N_N = 0; \quad \sum_N R^{a_1 \dots a_5 N}_N = 0, \quad R^{[a_1 \dots a_4, b]} = 0; \quad (2.1.2)$$

$$R^{[a_1 \dots a_5, b] MN} = 0; \quad R^{a_1 \dots a_6}_{[MN, P]} = 0, \quad (2.1.3)$$

The generators can be given a level, which in 7 dimensions, is the number of up indices minus the number of down  $SL(7)$  indices, and the semi-colons between the generators in equation (2.1.1) represent an increase in the level.

We begin by explaining how the algebra in seven dimensions was derived. In general, the algebra of  $E_{11} \otimes_s l_1$  can be written

$$[R^\alpha, R^\beta] = f^{\alpha\beta}{}_\gamma R^\gamma, \quad (2.1.4)$$

$$[R^\alpha, l_A] = -(D^\alpha)_A{}^B l_B, \quad (2.1.5)$$

where  $(D^\alpha)_A{}^B$  is the matrix of the first fundamental (vector) representation of  $E_{11}$  which satisfies

$$[D^\alpha, D^\beta] = f^{\alpha\beta}{}_\gamma D^\gamma. \quad (2.1.6)$$

We note that the commutators preserve the level and additionally are preserved under the action of the Cartan involution

$$I_c(R^\alpha) = (-1)^{\text{level}} R^{-\alpha}, \quad (2.1.7)$$

except for level zero which carries a minus sign. This will provide a useful check in the following derivation of the algebra.

The generators of the  $GL(7)$  algebra are denoted by  $K^a_b$ ,  $a, b = 1, \dots, 7$  satisfy the commutator

$$[K^a_b, K^c_d] = \delta^c_b K^a_d - \delta^a_d K^c_b, \quad (2.1.8)$$

and similarly, the generators of the  $SL(5)$  algebra,  $R^M_N$ , satisfy

$$[R^M_N, R^P_Q] = \delta^P_N R^M_Q - \delta^M_Q R^P_N, \quad (2.1.9)$$

We choose the remaining generators to be irreducible representations of  $GL(7) \times SL(5)$  and hence they satisfy the constraints in equation (2.1.2). Since the generators are representations of  $GL(7)$  and  $SL(5)$ , the commutators with the  $K^a_b$  and  $R^M_N$  generators are determined. For example, we have at level 1,

$$[K^a_b, R^{cMN}] = \delta^c_b R^{aMN}, \quad (2.1.10)$$

and at level -1, we have

$$[K^a_b, R_{cMN}] = -\delta^a_c R_{bMN}, \quad (2.1.11)$$

The other level generators follow a similar pattern in terms of how the spacetime generator acts on the upper and lower indices.

The action of the spacetime  $SL(7)$  is

$$[K^a_b, K^c_d] = \delta_b^c K^a_d - \delta_d^a K^c_b, \quad (2.1.12)$$

$$[K^a_b, R^M_N] = 0, \quad (2.1.13)$$

$$[K^a_b, R^{cMN}] = \delta_b^c R^{aMN}, \quad (2.1.14)$$

$$[K^a_b, R^{cd}_M] = 2\delta_b^{[c} R^{a|d]}_M, \quad (2.1.15)$$

$$[K^a_b, R^{c_1 c_2 c_3 M}] = 3\delta_b^{[c_1} R^{a|c_2 c_3]M}, \quad (2.1.16)$$

$$[K^a_b, R^{c_1 \dots c_4}_{PQ}] = 4\delta_b^{[c_1} R^{a|c_2 c_3 c_4]}_{PQ}, \quad (2.1.17)$$

$$[K^a_b, R^{c_1 \dots c_5 M}_N] = 5\delta_b^{[c_1} R^{a|c_2 \dots c_5]M}_N, \quad (2.1.18)$$

$$[K^a_b, R^{c_1 \dots c_4, d}] = 4\delta_b^{[c_1} R^{a|c_2 c_3 c_4], d} - 4\delta_b^d R^{a[c_1 c_2 c_3, c_4]}. \quad (2.1.19)$$

The action of  $SL(5)$

$$[R^M_N, R^P_Q] = \delta_N^P R^M_Q - \delta_Q^M R^P_N, \quad (2.1.20)$$

$$[R^M_N, R^{aPQ}] = 2\delta_N^{[P} R^{a|M|Q]} - \frac{2}{5}\delta_N^M R^{aPQ}, \quad (2.1.21)$$

$$[R^M_N, R^{ab}_P] = -\delta_P^M R^{ab}_N + \frac{1}{5}\delta_N^M R^{ab}_P, \quad (2.1.22)$$

$$[R^M_N, R^{a_1 a_2 a_3 P}] = \delta_N^P R^{a_1 a_2 a_3 M} - \frac{1}{5}\delta_N^M R^{a_1 a_2 a_3 P}, \quad (2.1.23)$$

$$[R^M_N, R^{a_1 \dots a_4}_{PQ}] = -2\delta_{[P}^M R^{a_1 \dots a_4}_{N|Q]} + \frac{2}{5}\delta_N^M R^{a_1 \dots a_4}_{PQ}, \quad (2.1.24)$$

$$[R^M_N, R^{a_1 \dots a_5 P}_Q] = \delta_N^P R^{a_1 \dots a_5 M}_Q - \delta_Q^M R^{a_1 \dots a_5 P}_N, \quad (2.1.25)$$

$$[R^M_N, R^{a_1 \dots a_4, b}] = 0, \quad (2.1.26)$$

We will calculate the  $E_{11}$  algebra up to level  $\pm 5$ . To find the right hand side of the commutators of two generators we write down all possible generators of the required level in such a way that it transforms in the same way under  $GL(7) \times SL(5)$  as the left-hand side of the commutator. We then use the Jacobi identities to fix the coefficient in front of relevant generators. As an example, we find that the commutator of the level 1 generator  $R^{aMN}$  with itself leads to a generator of level two. Looking at equation (2.1.1), we find that the only such candidate is the generator  $R^{ab}_R$  and so

$$[R^{aMN}, R^{bPQ}] \propto R^{ab}_R, \quad (2.1.27)$$

Demanding that the level two generator occur so as to have the same  $GL(7) \times SL(5)$  as the left-hand side we find that the only possibility is given by

$$[R^{aMN}, R^{bPQ}] = \varepsilon^{MNPQR} R^{ab}{}_R. \quad (2.1.28)$$

The coefficient in front of the level two generator can be fixed to be any number and this determines the normalisation with which the level two generator enters the algebra; we took the coefficient to be one.

We notice that up to level 4, there is only one generator at each level and so this is the only generator that can occur in commutators that result in level four generators. At level five there are two generators and both of these can enter the commutator. For example, if we consider the commutator of the level one generator with the level four generator, we find that their result, taking account that we must have the same  $GL(7) \times SL(5)$  representations on both sides of the equation, must be given by

$$[R^{a_1MN}, R^{a_2 \dots a_5}{}_{PQ}] = -2\delta_{[P}^{[M} R^{a_1 \dots a_5]N]}{}_{Q]} + \delta_{PQ}^{MN} R^{a_2 \dots a_5, a_1}. \quad (2.1.29)$$

We can choose the coefficients in front of the level five generators to be as above as this is the first time we have encountered them and this choice fixes their normalisation. To find the commutator of the level two and level three generators we use the Jacobi identity

$$[[R^{a_1 a_2}{}_M, R^{a_3 a_4}{}_N], R^{a_5 PQ}] + \text{cyclic} = 0, \quad (2.1.30)$$

as well as the previously derived result for the commutator of the two level two generators given below. We find that

$$[R^{a_1 a_2}{}_M, R^{a_3 a_4 a_5 N}] = R^{a_1 \dots a_5 N}{}_M + 2\delta_R^N R^{a_3 a_4 a_5} [a_1, a_2] \quad (2.1.31)$$

Using the above procedure the commutators of the positive level generators up to level five are given as follows [10]. The commutators formed by repeated use of the level one generator  $R^{aMN}$  are given by

$$[R^{aMN}, R^{bPQ}] = \varepsilon^{MNPQR} R^{ab}{}_R, \quad (2.1.32)$$

$$[R^{aMN}, R^{b_1 b_2}{}_P] = \delta_P^{[M} R^{ab_1 b_2]N}, \quad (2.1.33)$$

$$[R^{a_1 a_3}{}_M, R^{a_3 a_4}{}_N] = R^{a_1 \dots a_4}{}_{MN}, \quad (2.1.34)$$

$$[R^{a_1 MN}, R^{a_2 a_3 a_4 P}] = \varepsilon^{MNPQR} R^{a_1 \dots a_4}{}_{QR}, \quad (2.1.35)$$

$$[R^{a_1 a_2}{}_M, R^{a_3 a_4 a_5 N}] = R^{a_1 \dots a_5 N}{}_M + 2\delta_R^N R^{a_3 a_4 a_5} [a_1, a_2], \quad (2.1.36)$$

$$[R^{a_1 MN}, R^{a_2 \dots a_5}{}_{PQ}] = -2\delta_{[P}^{[M} R^{a_1 \dots a_5]N]}{}_{Q]} + \delta_{PQ}^{MN} R^{a_2 \dots a_5, a_1}. \quad (2.1.37)$$

The coefficients can be chosen as above and this fixes the normalisations of all the generators.

The action of the Cartan involution was given in equation (2.1.7), and so

$$\begin{aligned} I_c(K^a_b) &= -K^b_a, \quad I_c(R^M_N) = -R^N_M, \\ I_c(R^{aMN}) &= -R_{aMN}, \quad I_c(R^{a_1 a_2}_M) = +R_{a_1 a_2}^M, \text{ etc.} \end{aligned} \quad (2.1.38)$$

As a result the commutators of the negative level generators with themselves can be found from those above using the Cartan involution. For example

$$[R_{aMN}, R_{bPQ}] = \varepsilon_{MNPQR} R_{ab}^R, \quad (2.1.39)$$

$$[R_{aMN}, R_{b_1 b_2}^P] = \delta_{[M}^P R_{ab_1 b_2 N]}, \quad \text{etc} \quad (2.1.40)$$

The action of  $\text{SL}(7)$  on the negative level generators is given by

$$[K^a_b, R_{cMN}] = -\delta_c^a R_{bMN}, \quad (2.1.41)$$

$$[K^a_b, R_{cd}^M] = -2\delta_{[c}^a R_{b|d]}^M, \quad (2.1.42)$$

$$[K^a_b, R_{a_1 a_2 a_3 M}] = -3\delta_{[a_1}^a R_{b|a_2 a_3]M}, \quad (2.1.43)$$

$$[K^a_b, R_{c_1 \dots c_4}^{PQ}] = -4\delta_{[c_1}^a R_{b|c_2 c_3 c_4]}^{PQ}, \quad (2.1.44)$$

$$[K^a_b, R_{c_1 \dots c_5 M}^N] = -5\delta_{[c_1}^a R_{b|c_2 \dots c_5]M}^N, \quad (2.1.45)$$

$$[K^a_b, R_{c_1 \dots c_4, d}] = -4\delta_{[c_1}^a R_{b|c_2 c_3 c_4], d} + 4\delta_d^a R_{b[c_1 c_2 c_3, c_4]}. \quad (2.1.46)$$

While the action of  $\text{SL}(5)$  is

$$[R^M_N, R_{aPQ}] = -2\delta_{[P}^M R_{a|N|Q]} + \frac{2}{5}\delta_N^M R_{aPQ}, \quad (2.1.47)$$

$$[R^M_N, R_{a_1 a_2}^P] = \delta_N^P R_{a_1 a_2}^M - \frac{1}{5}\delta_N^M R_{a_1 a_2}^P, \quad (2.1.48)$$

$$[R^M_N, R_{a_1 a_2 a_3 P}] = -\delta_P^M R_{a_1 a_2 a_3 N} + \frac{1}{5}\delta_N^M R_{a_1 a_2 a_3 P}, \quad (2.1.49)$$

$$[R^M_N, R_{a_1 a_2 a_3 P}] = -\delta_P^M R_{a_1 a_2 a_3 N} + \frac{1}{5}\delta_N^M R_{a_1 a_2 a_3 P}, \quad (2.1.50)$$

$$[R^M_N, R_{a_1 \dots a_4}^{PQ}] = 2\delta_N^{[P} R_{a_1 \dots a_4}^{N|Q]} - \frac{2}{5}\delta_N^M R_{a_1 \dots a_4}^{PQ}, \quad (2.1.51)$$

$$[R^M_N, R_{a_1 \dots a_5 P}^Q] = -\delta_P^M R_{a_1 \dots a_5 N}^Q + \delta_N^Q R_{a_1 \dots a_5 P}^M, \quad (2.1.52)$$

$$[R^M_N, R_{a_1 \dots a_4, b}] = 0. \quad (2.1.53)$$

We now consider the commutators of positive with negative commutators. The generators are all normalised and we can use the Jacobi identities to determine all of these



commutators. For example by taking the Jacobi identity involving two level one generators and one level -1 generator we find that the following two commutators

$$[R^{aMN}, R_{bPQ}] = 4\delta_b^a \delta_{[P}^{[M} R^{N]}_{Q]} + \delta_{PQ}^{MN} (2K^a_b - \frac{2}{5}\delta_b^a \sum_c K^c_c) , \quad (2.1.54)$$

$$[R^{a_1 a_2}_M, R_{aPQ}] = -\varepsilon_{MPQRS} \delta_b^{[a_1} R^{a_2]RS} , \quad (2.1.55)$$

The best method is to take the coefficients in these two equations to be arbitrary and then applying the Jacobi identity. Applying the Cartan involution to equation (2.1.55) we find that

$$[R^{aMN}, R_{a_1 a_2}^P] = \varepsilon^{MNPQR} \delta_{[a_1}^a R_{a_2]QR} . \quad (2.1.56)$$

Similarly using the relevant the Jacobi identities we find that

$$[R^{a_1 a_2}_M, R_{b_1 b_2}^N] = 2\delta_{b_1 b_2}^{a_1 a_2} R^N_M - 4\delta_M^N \delta_{[b_1}^{[a_1} K^{a_2]}_{b_2]} + \frac{4}{5}\delta_M^N \delta_{b_1 b_2}^{a_1 a_2} \sum_e K^e_e , \quad (2.1.57)$$

While the commutators involving the level  $\pm 3$  generators are given by

$$[R^{a_1 a_2 a_3 M}, R_{bRS}] = 12\delta_b^{[a_1} \delta_{[R}^M R^{a_2 a_3]}_{S]} , \quad (2.1.58)$$

$$[R_{a_1 a_2 a_3 M}, R^{bRS}] = 12\delta_{[a_1}^b \delta_M^{[R} R^{a_2 a_3]}_{S]} , \quad (2.1.59)$$

$$[R^{a_1 a_2 a_3 M}, R_{b_1 b_2}^N] = 12\delta_{b_1 b_2}^{[a_1 a_2} R^{a_3]MN} , \quad (2.1.60)$$

$$[R_{a_1 a_2 a_3 N}, R^{b_1 b_2}_M] = 12\delta_{[a_1 a_2}^{b_1 b_2} R_{a_3]MN} , \quad (2.1.61)$$

$$[R^{a_1 a_2 a_3 M}, R_{b_1 b_2 b_3 N}] = 24\delta_{b_1 b_2 b_3}^{a_1 a_2 a_3} R^M_N + 72\delta_N^M \delta_{[b_1 b_2}^{[a_1 a_2} K^{a_3]}_{b_3]} - \frac{72}{5}\delta_{b_1 b_2 b_3}^{a_1 a_2 a_3} \sum_e K^e_e . \quad (2.1.62)$$

The commutators involving level  $\pm 4$  generators are given by

$$[R^{a_1 \dots a_4}_{MN}, R_{bPQ}] = -2\varepsilon_{MNPQR} \delta_b^{[a_1} R^{a_2 a_3 a_4]}_{R]} , \quad (2.1.63)$$

$$[R_{a_1 \dots a_4}^{MN}, R^{bPQ}] = -2\varepsilon^{MNPQR} \delta_{[a_1}^b R_{a_2 a_3 a_4]}_{R]} , \quad (2.1.64)$$

$$[R^{a_1 \dots a_4}_{MN}, R_{b_1 b_2}^P] = 24\delta_M^P \delta_{b_1 b_2}^{[a_1 a_2} R^{a_3 a_4]}_N , \quad (2.1.65)$$

$$[R_{a_1 \dots a_4}^{MN}, R^{b_1 b_2}_P] = 24\delta_P^M \delta_{[a_1 a_2}^{b_1 b_2} R_{a_3 a_4]}^N , \quad (2.1.66)$$

$$[R^{a_1 \dots a_4}_{MN}, R_{b_1 b_2 b_3 P}] = -24\varepsilon_{MNPQR} \delta_{b_1 b_2 b_3}^{[a_1 a_2 a_3} R^{a_4]}_{PQ} , \quad (2.1.67)$$

$$[R_{a_1 \dots a_4}^{MN}, R^{b_1 b_2 b_3 P}] = -24\varepsilon^{MNPQR} \delta_{[a_1 a_2 a_3}^{b_1 b_2 b_3} R_{a_4]}_{PQ} , \quad (2.1.68)$$

$$[R^{a_1 \dots a_4}_{MN}, R_{b_1 \dots b_4}^{PQ}] = 96\delta_{b_1 \dots b_4}^{a_1 \dots a_4} \delta_{[M}^{[P} R^{Q]}_{N]} ,$$

$$-192\delta_{MN}^{PQ}\delta_{[b_1b_2b_3}^{[a_1a_2a_3}K^{a_4]}_{b_4]} + \frac{192}{5}\delta_{MN}^{PQ}\delta_{b_1\dots b_4}^{a_1\dots a_4}K^e_e. \quad (2.1.69)$$

Finally, the commutators involving level  $\pm 5$  generators are given by

$$[R^{a_1\dots a_5M}_N, R_{bPQ}] = 20\delta_{[P}^M\delta_b^{[a_1}R^{a_2\dots a_5]}_{N|Q]} - 4\delta_N^M\delta_b^{[a_1}R^{a_2\dots a_5]}_{PQ}, \quad (2.1.70)$$

$$[R_{a_1\dots a_5M}^N, R^{bPQ}] = 20\delta_M^{[P]}\delta_{[a_1}^bR^{a_2\dots a_5]}_{N|Q]} - 4\delta_M^N\delta_{[a_1}^bR^{a_2\dots a_5]}_{PQ}, \quad (2.1.71)$$

$$[R^{a_1\dots a_5M}_N, R_{b_1b_2}^P] = 20\delta_N^P\delta_{b_1b_2}^{[a_1a_2}R^{a_3a_4a_5]}_M - 4\delta_N^M\delta_{b_1b_2}^{[a_1a_2}R^{a_3a_4a_5]}_P, \quad (2.1.72)$$

$$[R_{a_1\dots a_5M}^N, R^{b_1b_2}_P] = 20\delta_P^N\delta_{[a_1a_2}^{b_1b_2}R^{a_3a_4a_5]}_M - 4\delta_M^N\delta_{[a_1a_2}^{b_1b_2}R^{a_3a_4a_5]}_P, \quad (2.1.73)$$

$$[R^{a_1\dots a_5M}_N, R_{b_1b_2b_3P}] = 240\delta_P^M\delta_{b_1b_2b_3}^{[a_1a_2a_3}R^{a_4a_5]}_N - 48\delta_N^M\delta_{b_1b_2b_3}^{[a_1a_2a_3}R^{a_4a_5]}_P, \quad (2.1.74)$$

$$[R_{a_1\dots a_5M}^N, R^{b_1b_2b_3}_P] = 240\delta_M^P\delta_{[a_1a_2a_3}^{b_1b_2b_3}R^{a_4a_5]}_N - 48\delta_M^N\delta_{[a_1a_2a_3}^{b_1b_2b_3}R^{a_4a_5]}_P, \quad (2.1.75)$$

$$[R^{a_1\dots a_5M}_N, R_{b_1\dots b_4}^{PQ}] = 480\delta_N^{[P]}\delta_{b_1\dots b_4}^{[a_1\dots a_4}R^{a_5]}_{M|Q]} - 96\delta_N^M\delta_{b_1\dots b_4}^{[a_1\dots a_4}R^{a_5]}_{PQ}, \quad (2.1.76)$$

$$[R_{a_1\dots a_5M}^N, R^{b_1\dots b_4}_{PQ}] = 480\delta_{[P}^N\delta_{a_1\dots a_4}^{b_1\dots b_4}R^{a_5]}_{M|Q]} - 96\delta_M^N\delta_{a_1\dots a_4}^{b_1\dots b_4}R^{a_5]}_{PQ}, \quad (2.1.77)$$

$$\begin{aligned} & [R^{a_1\dots a_5M}_N, R_{b_1\dots b_5Q}^P] = -480\delta_{b_1\dots b_5}^{a_1\dots a_5}(\delta_Q^M R^P_N - \delta_N^P R^M_Q) \\ & + 480(5\delta_N^P\delta_Q^M - \delta_Q^P\delta_N^M)\delta_{[b_1\dots b_4}^{[a_1\dots a_4}K^{a_5]}_{b_5]} - 96(5\delta_N^P\delta_Q^M - \delta_Q^P\delta_N^M)\delta_{b_1\dots b_5}^{a_1\dots a_5}K^e_e, \end{aligned} \quad (2.1.78)$$

$$[R^{a_1\dots a_4,b}, R_{cMN}] = -\frac{8}{5}\delta_c^b R^{a_1\dots a_4}_{MN} + \frac{8}{5}\delta_c^{[a_1}R^{a_2a_3a_4]b}_{MN}, \quad (2.1.79)$$

$$[R_{a_1\dots a_4,b}, R^{cMN}] = -\frac{8}{5}\delta_b^c R_{a_1\dots a_4}^{MN} + \frac{8}{5}\delta_{[a_1}^c R_{a_2a_3a_4]b}^{MN}, \quad (2.1.80)$$

$$[R^{a_1\dots a_4,b}, R_{c_1c_2}^M] = -\frac{24}{5}\delta_{c_1c_2}^{[a_1|b}R^{a_2a_3a_4]}_M - \frac{24}{5}\delta_{b_1b_2}^{[a_1a_2}R^{a_3a_4]bM}, \quad (2.1.81)$$

$$[R_{a_1\dots a_4,b}, R^{c_1c_2}_M] = -\frac{24}{5}\delta_{[a_1|b}^{c_1c_2}R_{a_2a_3a_4]}_M - \frac{24}{5}\delta_{[a_1a_2}^{b_1b_2}R_{a_3a_4]bM}, \quad (2.1.82)$$

$$[R^{a_1\dots a_4,b}, R_{c_1c_2c_3M}] = -\frac{288}{5}\delta_{c_1c_2c_3}^{[a_1a_2|b}R^{a_3a_4]}_M + \frac{288}{5}\delta_{c_1c_2c_3}^{[a_1a_2a_3}R^{a_4]b}_M, \quad (2.1.83)$$

$$[R_{a_1\dots a_4,b}, R^{c_1c_2c_3}_M] = -\frac{288}{5}\delta_{[a_1a_2|b}^{c_1c_2c_3}R_{a_3a_4]}^M + \frac{288}{5}\delta_{[a_1a_2a_3}^{c_1c_2c_3}R_{a_4]b}^M, \quad (2.1.84)$$

$$[R^{a_1\dots a_4,b}, R_{c_1\dots c_4}^{MN}] = -\frac{192}{5}\delta_{c_1\dots c_4}^{[a_1a_2a_3|b}R^{a_4]}_{MN} - \frac{192}{5}\delta_{c_1\dots c_4}^{a_1\dots a_4}R^{bMN}, \quad (2.1.85)$$

$$[R_{a_1\dots a_4,b}, R^{c_1\dots c_4}_{MN}] = -\frac{192}{5}\delta_{[a_1a_2a_3|b}^{c_1\dots c_4}R_{a_4]}_{MN} + -\frac{192}{5}\delta_{a_1\dots a_4}^{c_1\dots c_4}R_{bMN}, \quad (2.1.86)$$

$$\begin{aligned} & [R^{a_1\dots a_4,b}, R_{c_1\dots c_4,d}] = \frac{384}{5}(\delta_{c_1\dots c_4}^{a_1\dots a_4}K^b_d + \delta_{c_1\dots c_4}^{[a_1a_2a_3|b}K^{a_4]}_d + \delta_{[c_1c_2c_3|d}^{a_1\dots a_4}K^b_{|c_4]} \\ & + 5\delta_d^b\delta_{[c_1c_2c_3}^{[a_1a_2a_3}K^{a_4]}_{c_4]} - 4\delta_{[c_1c_2c_3|d}^{[a_1a_2a_3|b}K^{a_4]}_{|c_4]}) - \frac{384}{5}(\delta_{c_1\dots c_4}^{a_1\dots a_4}\delta_d^b + \delta_{c_1\dots c_4}^{[a_1a_2a_3|b}\delta_d^{a_4]})K^e_e. \end{aligned} \quad (2.1.87)$$

Finally, we find the commutators involving the level 6 generators. We begin with the commutators of level 5 with level 1

$$[R^{aMN}, R^{b_1 \dots b_5 P}_Q] = 2\varepsilon^{MNP RS} R^{ab_1 \dots b_5}_{RS, Q} + 8\delta_Q^{[N} R^{ab_1 \dots b_5] (|P|M)} + 20\delta_Q^{[N} R^{b_1 \dots b_5, a|P|M]} + 4\delta_Q^P R^{b_1 \dots b_5, aMN}, \quad (2.1.88)$$

$$[R^{aMN}, R^{b_1 \dots b_4, c}] = 8R^{b_1 \dots b_4 a, cMN} - R^{ac[b_1 b_2 b_3, b_4]MN}, \quad (2.1.89)$$

and then the commutators of the level 6 generators with level -1 are

$$[R_{aMN}, R^{b_1 \dots b_6}_{PQ, R}] = \varepsilon_{MNP RS} [\delta_a^{[b_1} R^{b_2 \dots b_6] S}_Q] + \varepsilon_{MNP QS} \delta_a^{[b_1} R^{b_2 \dots b_6] S}_R \quad (2.1.90)$$

$$[R_{aMN}, R^{b_1 \dots b_6 (PQ)}] = -3\delta_{[N}^{(Q} \delta_a^{[b_1} R^{b_2 \dots b_6] P)}_{M]} , \quad (2.1.91)$$

$$[R_{aMN}, R^{b_1 \dots b_5, cPQ}] = -\frac{1}{3}\delta_{[R}^{[Q} \delta_a^{[b_1} R^{b_2 \dots b_5], cP]}_{M]} - \frac{1}{3}\delta_{[R}^{[Q} \delta_a^c R^{b_1 \dots b_5 P]}_{M]} + \delta_{PQ}^{MN} \delta_a^{[b_1} R^{b_2 \dots b_5], c} . \quad (2.1.91)$$

## 2.2 The commutators of $E_{11}$ with the vector representation

The elements of the vector ( $l_1$ ) representation when decomposed into representations of  $SL(7) \otimes SL(5)$  are given by

$$P_a; \quad Z^{MN}; \quad Z^a_M; \quad Z^{a_1 a_2 M}; \quad Z^{a_1 a_2 a_3}_{MN}; \quad Z^{a_1 a_2 a_3, b}; \quad Z^{a_1 \dots a_4}; \quad Z^{a_1 \dots a_4 M}_N; \\ Z^{a_1 \dots a_5 MN}, \quad Z^{a_1 \dots a_5 (MN)}, \quad Z^{a_1 \dots a_5}_{MN, P}, \quad Z^{a_1 \dots a_4, bMN}, \dots \quad (2.2.1)$$

These belong to irreducible representations of  $SL(7) \otimes SL(5)$  and our index conventions are as given earlier for the  $E_{11}$  generators. We now regard these as generators whose commutator is given by equation (2.1.5). They have a level that is the number of up minus down indices plus one. The generators in the vector representation at low levels and the coordinates they lead to in the non-linear realisation we given in references [11,12,13].

As they belong to representation of  $SL(7)$ , their commutators of the generators of  $SL(7)$  are given by

$$[K^a_b, P_c] = -\delta_c^a P_b + \frac{1}{2}\delta_b^a P_c, \quad (2.2.2)$$

$$[K^a_b, Z^{MN}] = \frac{1}{2}\delta_b^a Z^{MN}, \quad (2.2.3)$$

$$[K^a_b, Z^c_M] = \delta_b^c Z^a_M + \frac{1}{2}\delta_b^a Z^c_M, \quad (2.2.4)$$

$$[K^a_b, Z^{a_1 a_2 M}] = 2\delta_b^{[a_1} Z^{a|a_2]M} + \frac{1}{2}\delta_b^a Z^{a_1 a_2 M}, \quad (2.2.5)$$

$$[K^a_b, Z^{b_1 b_2 b_3}_{PQ}] = 3\delta_b^{[b_1]} Z^{a|b_2 b_3]}_{PQ} + \frac{1}{2}\delta^a_b Z^{b_1 b_2 b_3}_{PQ} , \quad (2.2.6)$$

$$[K^a_b, Z^{c_1 \dots c_4 M}_N] = 4\delta_b^{[c_1]} Z^{a|c_2 c_3 c_4]}_M + \frac{1}{2}\delta^a_b Z^{c_1 \dots c_4 M}_N , \quad (2.2.7)$$

$$[K^a_b, Z^{c_1 c_2 c_3, d}] = 3\delta_b^{[c_1]} Z^{a|c_2 c_3, d]} + \delta_b^d Z^{c_1 c_2 c_3, a} + \frac{3}{2}\delta_b^a Z^{d[c_1 c_2, c_3]} , \quad (2.2.7)$$

$$[K^a_b, Z^{c_1 \dots c_4}] = 4\delta_b^{[c_1]} Z^{a|c_2 c_3]} + \frac{1}{2}\delta_b^a Z^{c_1 \dots c_4} . \quad (2.2.8)$$

While with the generators of  $SL(5)$  we have

$$[R^M_N, P_a] = 0 , \quad (2.2.9)$$

$$[R^M_N, Z^{PQ}] = 2\delta_N^{[P} Z^{M|Q]} - \frac{2}{5}\delta_N^M Z^{PQ} , \quad (2.2.10)$$

$$[R^M_N, Z^a_P] = -\delta_P^M Z^a_N + \frac{1}{5}\delta_N^M Z^a_P , \quad (2.2.11)$$

$$[R^M_N, Z^{a_1 a_2 P}] = \delta_N^P Z^{a_1 a_2 M} - \frac{1}{5}\delta_N^M Z^{a_1 a_2 P} , \quad (2.2.12)$$

$$[R^M_N, Z^{a_1 a_2 a_3}_{PQ}] = -2\delta_{[P}^M Z^{a_1 a_2 a_3]}_{N|Q]} + \frac{2}{5}\delta_N^M Z^{a_1 a_2 a_3}_{PQ} , \quad (2.2.13)$$

$$[R^M_N, Z^{c_1 \dots c_4 P}_Q] = \delta_N^P Z^{c_1 \dots c_4 M}_Q - \delta_Q^M Z^{c_1 \dots c_4 P}_N , \quad (2.2.14)$$

$$[R^M_N, Z^{c_1 c_2 c_3, d}] = 0 , \quad (2.2.15)$$

$$[R^M_N, Z^{c_1 \dots c_4}] = 0 , \quad (2.2.16)$$

The commutators of the  $E_{11}$  generators with those of the vector representation can be found using similar arguments to those used to find the commutators of  $E_{11}$ . The commutators must preserve the level and their  $SL(7) \otimes SL(5)$  character must be the same on both sides of the commutator. The repeated commutators of the level one  $E_{11}$  generator are used to define the normalisation of the  $l_1$  generators as follows

$$[R^{aMN}, P_b] = \delta_b^a Z^{MN} , \quad (2.2.17)$$

$$[R^{aMN}, Z^{PQ}] = -\varepsilon^{MNPQR} Z^a_R , \quad (2.2.18)$$

$$[R^{aMN}, Z^b_P] = 2\delta_P^{[M} Z^{abN]} , \quad (2.2.19)$$

$$[R^{aMN}, Z^{b_1 b_2 P}] = \varepsilon^{MNP RS} Z^{ab_1 b_2}_{RS} , \quad (2.2.20)$$

$$[R^{aMN}, Z^{b_1 b_2 b_3}_{PQ}] = \delta_{PQ}^{MN} (Z^{b_1 b_2 b_3, a} + Z^{b_1 b_2 b_3 a}) + \delta_{[P}^{[M} Z^{ab_1 b_2 b_3|N]}_{Q]} . \quad (2.2.21)$$

Using the  $E_{11}$  commutators and the Jacobi identities we can find the commutators involving the positive  $E_{11}$  generators to be as follows

$$[R^{a_1 a_2}_P, P_b] = 2\delta_b^{[a_1} Z^{a_2]}_P , \quad (2.2.22)$$

$$[R^{a_1 a_2}{}_P, Z^{RS}] = 2\delta_P^R Z^{a_1 a_2 S} , \quad (2.2.23)$$

$$[R^{a_1 a_2}{}_P, Z^b{}_S] = 2Z^{a_1 a_2 b}{}_P{}_S , \quad (2.2.24)$$

$$[R^{a_1 a_2}{}_P, Z^{b_1 b_2 R}] = -2\delta_P^R (Z^{a_1 a_2 b_1 b_2} + Z^{b_1 b_2 [a_1, a_2]}) - \frac{1}{2} Z^{a_1 a_2 b_1 b_2 R}{}_P , \quad (2.2.25)$$

For example to find the first relation we use the Jacobi identity  $[[R^{a_1 MN}, R^{a_2 PQ}], P_b] + \dots = 0$ .

Similarly the commutators involving the level three  $E_{11}$  generators are given by

$$[R^{a_1 a_2 a_3 M}, P_b] = -6\delta_b^{[a_1} Z^{a_2 a_3]M} , \quad (2.2.26)$$

$$[R^{a_1 a_2 a_3 M}, Z^{PQ}] = -2\varepsilon^{MPQRS} Z^{a_1 a_2 a_3}{}_{RS} , \quad (2.2.27)$$

$$[R^{a_1 a_2 a_3 M}, Z^b{}_Q] = Z^{a_1 a_2 a_3 b M}{}_Q + 6\delta_Q^M Z^{b[a_1 a_2, a_3]} - 6\delta_Q^M Z^{a_1 a_2 a_3 b} , \quad (2.2.28)$$

while those involving the level four generators by

$$[R^{a_1 \dots a_4}{}_{MN}, P_b] = 8\delta_b^{[a_1} Z^{a_2 a_3 a_4]}{}_{MN} , \quad (2.2.29)$$

$$[R^{a_1 \dots a_4}{}_{MN}, Z^{PQ}] = 8\delta_{MN}^{PQ} Z^{a_1 \dots a_4} + 2\delta_{[M}^{[P} Z^{a_1 \dots a_4 | Q]}{}_{|N]} , \quad (2.2.30)$$

and the commutators with level five generators are given by

$$[R^{a_1 \dots a_5 M}{}_N, P_c] = 5\delta_c^{[a_1} Z^{a_2 \dots a_5]M}{}_N , \quad (2.2.31)$$

$$[R^{a_1 \dots a_4, b}{}_c, P_c] = 8\delta_c^{[a_1} Z^{a_2 a_3 a_4], b} + 8(\delta_c^{[a_1} Z^{a_2 a_3 a_4]b} - \delta_c^b Z^{a_1 \dots a_4}) . \quad (2.2.32)$$

We now turn to consider the commutators of the negative level  $E_{11}$  generators with those of the vector representation. As the vector representation is a lowest weight representation we have by definition the commutator

$$[R_{aMN}, P_b] = 0 , \quad (2.2.33)$$

By considering the Jacobi identity  $[R_{aMN}, [R^{bPQ}, P_c]] + \dots = 0$  we find the commutator

$$[R_{aMN}, Z^{PQ}] = 2\delta_{MN}^{PQ} P_a , \quad (2.2.34)$$

Using similar arguments we find that the commutators of level minus one  $E_{11}$  generators with those of the vector representation take the form

$$[R_{aMN}, Z^b{}_P] = -\frac{1}{2}\delta_b^a \varepsilon_{MNPQR} Z^{QR} , \quad (2.2.35)$$

$$[R_{aMN}, Z^{b_1 b_2 P}] = -4\delta_{[M}^P \delta_a^{[b_1} Z^{b_2]}{}_{N]} , \quad (2.2.36)$$

$$[R_{aMN}, Z^{b_1 b_2 b_3}{}_{PQ}] = \frac{3}{2}\varepsilon_{MNPQR} \delta_a^{[b_1} Z^{b_2 b_3]}{}^R , \quad (2.2.37)$$

$$[R_{aMN}, Z^{c_1 c_2 c_3, b}] = \frac{3}{2}(\delta_a^{[c_1} Z^{c_2 c_3]b}{}_{MN} + \delta_a^b Z^{c_1 c_2 c_3}{}_{MN}) , \quad (2.2.38)$$

$$[R_{aMN}, Z^{c_1 \dots c_4}] = -\frac{2}{5}\delta_a^{[c_1} Z^{c_2 c_3 c_4]}{}_{MN} , \quad (2.2.39)$$

$$[R_{aMN}, Z^{c_1 \dots c_4 Q}{}_S] = -32(\delta_{[M}^Q \delta_a^{[c_1} Z^{c_2 c_3 c_4]}{}_{|N]S} + \frac{1}{5}\delta_S^Q \delta_a^{[c_1} Z^{c_2 c_3 c_4]}{}_{MN}) , \quad (2.2.40)$$

Using equation (2.1.40) and the corresponding Jacobi identity we find the commutators of the level minus two generators to be given by

$$[R_{a_1 a_2}{}^P, P_b] = 0 = [R_{a_1 a_2}{}^P, Z^{RS}] , \quad (2.2.41)$$

$$[R_{a_1 a_2}{}^P, Z^b{}_R] = 2\delta_R^P \delta_{[a_1}^b P_{a_2]} , \quad (2.2.42)$$

$$[R_{a_1 a_2}{}^P, Z^{b_1 b_2 R}] = -2\delta_{a_1 a_2}^{b_1 b_2} Z^{PR} , \quad (2.2.43)$$

$$[R_{a_1 a_2}{}^P, Z^{b_1 b_2 b_3}{}_{RS}] = -6\delta_{a_1 a_2}^{[b_1 b_2]} \delta_{[R}^P Z^{b_3]}{}_{|S]} , \quad (2.2.44)$$

$$[R_{a_1 a_2}{}^L, Z^{b_1 \dots b_4}] = \frac{6}{5}\delta_{a_1 a_2}^{[b_1 b_2} Z^{b_3 b_4]L} , \quad (2.2.45)$$

$$[R_{a_1 a_2}{}^L, Z^{b_1 b_2 b_3, c}] = -3(\delta_{a_1 a_2}^{[b_1 b_2} Z^{b_3]cL} + \delta_{a_1 a_2}^c Z^{b_1 b_2 b_3}{}^L) , \quad (2.2.46)$$

$$[R_{a_1 a_2}{}^L, Z^{b_1 \dots b_4 R}{}_S] = 24\delta_{a_1 a_2}^{[b_1 b_2]} (\delta_L^S Z^{b_3 b_4]R} - \frac{1}{5}\delta_S^R Z^{b_3 b_4]L}) , \quad (2.2.47)$$

while the commutators involving level minus three  $E_{11}$  generators are given by

$$[R_{a_1 a_2 a_3 P}, P_b] = 0 = [R_{a_1 a_2 a_3 P}, Z^{RS}] = [R_{a_1 a_2 a_3 P}, Z^b{}_S] , \quad (2.2.48)$$

$$[R_{a_1 a_2 a_3 M}, Z^{b_1 b_2 N}] = -12\delta_M^N \delta_{[a_1 a_2}^{b_1 b_2} P_{a_3]} , \quad (2.2.49)$$

$$[R_{a_1 a_2 a_3 M}, Z^{b_1 b_2 b_3}{}_{NP}] = -3\varepsilon_{MNPQR} \delta_{a_1 a_2 a_3}^{b_1 b_2 b_3} Z^{QR} , \quad (2.2.50)$$

$$[R_{a_1 a_2 a_3 M}, Z^{b_1 \dots b_4}] = -\frac{3! \cdot 3!}{5}\delta_{a_1 a_2 a_3}^{[c_1 c_2 c_3} Z^{c_4]}{}_M , \quad (2.2.51)$$

$$[R_{a_1 a_2 a_3 M}, Z^{b_1 b_2 b_3, c}] = 9(\delta_{a_1 a_2 a_3}^{b_1 b_2 b_3} Z^c{}_M + \delta_{a_1 a_2 a_3}^c Z^{b_1 b_2 b_3}{}_M) , \quad (2.2.52)$$

$$[R_{a_1 a_2 a_3 M}, Z^{b_1 \dots b_4 Q}{}_T] = 4 \cdot 4! (\delta_M^Q \delta_{a_1 a_2 a_3}^{[b_1 b_2 b_3} Z^{b_4]}{}_T - \frac{1}{5}\delta_T^Q \delta_{a_1 a_2 a_3}^{[b_1 b_2 b_3} Z^{b_4]}{}_M) . \quad (2.2.53)$$

The commutators of the level minus four  $E_{11}$  generators with the generators of the vector representation are given by

$$[R_{a_1 \dots a_4}{}^{S_1 S_2}, Z^{b_1 b_2 b_3}{}_{L_1 L_2}] = -4!\delta_{L_1 L_2}^{S_1 S_2} P_{[a_1} \delta_{a_2 a_3 a_4]}^{b_1 b_2 b_3} , \quad (2.2.54)$$

$$[R_{a_1 \dots a_4}{}^{S_1 S_2}, Z^{b_1 \dots b_4}] = -\frac{4!}{5}\delta_{a_1 \dots a_4}^{b_1 \dots b_4} Z^{S_1 S_2} , \quad (2.2.55)$$

$$[R_{a_1 \dots a_4} S_1 S_2, Z^{b_1 b_2 b_3, c}] = 0, \quad (2.2.56)$$

$$[R_{a_1 \dots a_4} S_1 S_2, Z^{b_1 \dots b_4} R_T] = 4 \cdot 4! \delta_{a_1 \dots a_4}^{b_1 \dots b_4} (\delta_T^{[S_1} Z^{S_2] R} + \frac{1}{5} \delta_T^R Z^{S_1 S_2}), \quad (2.2.57)$$

and finally with the level minus five  $E_{11}$  generators are given by

$$[R_{a_1 \dots a_5 R}^S, Z^{b_1 \dots b_4}] = 0, \quad (2.2.58)$$

$$[R_{a_1 \dots a_4, b}, Z^{c_1 \dots c_4}] = -\frac{48}{5} (P_b \delta_{a_1 \dots a_4}^{c_1 \dots c_4} + P_{[a_1} \delta_{b|a_2 a_3 a_4]}^{c_1 \dots c_4}), \quad (2.2.59)$$

$$[R_{a_1 \dots a_4, b}, Z^{c_1 c_2 c_3, d}] = 36 (P_{[a_1} \delta_{b|a_2 a_3 a_4]}^{[c_1} \delta^{c_2 c_3] d} + \delta_b^d P_{[a_1} \delta_{a_2 a_3 a_4]}^{c_1 c_2 c_3}), \quad (2.2.60)$$

$$[R_{a_1 \dots a_5 R}^S, Z^{b_1 b_2 b_3, c}] = 0, \quad (2.2.61)$$

$$[R_{a_1 \dots a_5 M}^N, Z^{b_1 \dots b_4} R_S] = -96 (\delta_M^N \delta_T^R - 5 \delta_T^N \delta_M^R) \delta_{[a_1 \dots a_4}^{b_1 \dots b_4} P_{a_5]}, \quad (2.2.62)$$

$$[R_{a_1 \dots a_4, b}, Z^{c_1 \dots c_4} M_N] = 0. \quad (2.2.63)$$

### 2.3 The Cartan involution invariant algebra, $I_c(E_{11})$

This algebra plays a crucial role in constructing the invariant dynamics. The algebra  $I_c(E_{11})$  at level zero is just the Cartan involution invariant subalgebra of  $GL(7) \otimes SL(5)$  which is  $SO(7) \otimes SO(5)$ . The Cartan involution invariant generators are

$$\begin{aligned} J^a_b &= K^a_b - K^b_a; \quad S^M_N = R^M_N - R^N_M; \\ S^{aMN} &= R^{aMN} - R_{aMN}; \quad S^{a_1 a_2}_M = R^{a_1 a_2}_M + R_{a_1 a_2}^M; \\ S^{a_1 a_2 a_3 M} &= R^{a_1 a_2 a_3 M} - R_{a_1 a_2 a_3 M}; \dots \end{aligned} \quad (2.3.1)$$

In the following, we will sometimes refer to these generators as 'even' generators.

The generators at level zero obey the algebra of  $SO(7) \otimes SO(5)$ :

$$[J^a_b, J^c_d] = \delta_b^c J^a_d - \delta_a^c J^b_d - \delta_a^d J^c_b + \delta_b^d J^c_a, \quad (2.3.2)$$

$$[S^M_N, S^P_Q] = \delta_N^P S^M_Q - \delta_M^P S^N_Q - \delta_Q^M S^P_N + \delta_Q^N S^P_M, \quad (2.3.3)$$

$$[J^a_b, S^M_N] = 0. \quad (2.3.4)$$

The commutators of the generators of  $SO(7) \otimes SO(5)$  with the other generators of  $I_c(E_{11})$  are determined by the representations to which the latter belong and are of standard form which is given by

$$[J^a_b, S^{cMN}] = \delta_b^c S^{aMN} - \delta_a^c S^{bMN}, \quad (2.3.5)$$

$$[J^a_b, S^{cd}_M] = 2\delta_b^{[c} S^{a|d]}_M - 2\delta_a^{[c} S^{b|d]}_M, \quad (2.3.6)$$

$$[J^a_b, S^{c_1 c_2 c_3 M}] = 3\delta_b^{[c_1} S^{a|c_2 c_3] M} - 3\delta_a^{[c_1} S^{b|c_2 c_3] M}, \quad (2.3.7)$$

$$[S^M_N, S^{aPQ}] = 2\delta_N^{[P} S^{a|M|Q]} - 2\delta_M^{[P} S^{a|N|Q]} , \quad (2.3.8)$$

$$[S^M_N, S^{ab}_P] = -\delta_P^M S^{ab}_N + \delta_P^N S^{ab}_M , \quad (2.3.9)$$

$$[S^M_N, S^{a_1 a_2 a_3 P}] = \delta_N^P S^{a_1 a_2 a_3 M} - \delta_M^P S^{a_1 a_2 a_3 N} , \quad (2.3.10)$$

The commutators of the generators of  $I_c(E_{11})$  are easily found by using the commutators of  $E_{11}$  given in section (2.1) and their definition of equation (2.3.1). We find that

$$[S^{aMN}, S^{bPQ}] = \varepsilon^{MNPQR} S^{ab}_R - 4\delta_b^a \delta_{[P}^{[M} S^{N]}_{Q]} - 2\delta_{PQ}^{MN} J^a_b , \quad (2.3.11)$$

$$[S^{aMN}, S^{b_1 b_2}_P] = \delta_P^{[M} S^{ab_1 b_2 N]} - \varepsilon^{MNPQR} \delta_a^{[b_1} S^{b_2]QR} , \quad (2.3.12)$$

$$[S^{aMN}, S^{b_1 b_2 b_3 P}] = 12\delta_a^{[b_1} \delta_{[M}^P S^{b_2 b_3]N]} + \varepsilon^{MNP L_1 L_2} S^{ab_1 b_2 b_3}_{L_1 L_2} , \quad (2.3.13)$$

$$[S^{a_1 a_2}_M, S^{b_1 b_2}_N] = S^{a_1 a_2 b_1 b_2}_{MN} - 2\delta_{b_1 b_2}^{a_1 a_2} S^M_N - 4\delta_N^M \delta_{[b_1}^{[a_1} J^{a_2]}_{b_2]} , \quad (2.3.14)$$

$$[S^{a_1 a_2}_M, S^{b_1 b_2 b_3 N}] = S^{a_1 a_2 b_1 b_2 b_3 N}_M - 12\delta_{a_1 a_2}^{[b_1 b_2} S^{b_3]MN} , \quad (2.3.15)$$

$$[S^{a_1 a_2 a_3 M}, S^{b_1 b_2 b_3 N}] = -24\delta_{b_1 b_2 b_3}^{a_1 a_2 a_3} S^M_N - 72\delta_N^M \delta_{[b_1 b_2}^{[a_1 a_2} J^{a_3]}_{b_3]} . \quad (2.3.16)$$

## 2.4 The $l_1$ representation with the representation of $I_c(E_{11})$

In this section we give the commutators with the  $I_c(E_{11})$  generators with those of the  $l_1$  representation. These are easily computed using the commutators of the generators of  $E_{11}$  with the vector representation which are given in section (2.2). The commutators of the generators of  $SO(7) \otimes SO(5)$  with the vector representation are given by

$$[J^a_b, P_c] = -\delta_c^a P_b + \delta_c^b P_a , \quad (2.4.1)$$

$$[J^a_b, Z^{MN}] = 0 , \quad (2.4.2)$$

$$[J^a_b, Z^c_M] = \delta_b^c Z^a_M - \delta_a^c Z^b_M , \quad (2.4.3)$$

$$[J^a_b, Z^{c_1 c_2 M}] = 2\delta_b^{[c_1} Z^{a|c_2]M} - 2\delta_a^{[c_1} Z^{b|c_2]M} , \quad (2.4.4)$$

$$[S^M_N, P_a] = 0 , \quad (2.4.5)$$

$$[S^M_N, Z^{PQ}] = 2\delta_N^{[P} Z^{M|Q]} - 2\delta_M^{[P} Z^{N|Q]} , \quad \text{etc} \quad (2.4.6)$$

The commutators of the generators of  $I_c(E_{11})$  involving level  $\pm 1$  generators with the vector representation are given by

$$[S^{aMN}, P_b] = \delta_b^a Z^{MN} , \quad (2.4.7)$$

$$[S^{aMN}, Z^{PQ}] = -\varepsilon^{MNPQR} Z^a_R - 2\delta_{MN}^{PQ} P_a , \quad (2.4.8)$$

$$[S^{aMN}, Z^b_P] = 2\delta_P^{[M} Z^{abN]} + \frac{1}{2}\delta_b^a \varepsilon_{MNPQR} Z^{QR} , \quad (2.4.9)$$

$$[S^{aMN}, Z^{b_1 b_2 P}] = \varepsilon^{MNP RS} Z^{ab_1 b_2}_{RS} + 4\delta_{[M}^P \delta_a^{[b_1} Z^{b_2]}_{N]} , \quad (2.4.10)$$



$$[S^{aMN}, Z^{b_1 b_2 b_3}{}_{PQ}] = \delta_{PQ}^{MN} (Z^{b_1 b_2 b_3, a} + Z^{b_1 b_2 b_3 a}) \\ + \delta_{[P}^{[M} Z^{ab_1 b_2 b_3]N]}{}_{Q]} - \frac{3}{2} \varepsilon_{MNPQR} \delta_a^{[b_1} Z^{b_2 b_3]R} , \quad (2.4.11)$$

$$[S^{aMN}, Z^{c_1 c_2 c_3, b}] = -\frac{3}{2} (\delta_a^{[c_1} Z^{c_2 c_3]b}{}_{MN} + \delta_a^b Z^{c_1 c_2 c_3}{}_{MN}) + \dots , \quad (2.4.12)$$

$$[S^{aMN}, Z^{c_1 \dots c_4}] = \frac{2}{5} \delta_a^{[c_1} Z^{c_2 c_3 c_4]}{}_{MN} + \dots , \quad (2.4.13)$$

$$[S^{aMN}, Z^{c_1 \dots c_4} Q_S] = 8 \cdot 4 (\delta_{[M}^Q \delta_a^{[c_1} Z^{c_2 c_3 c_4]}{}_{N]} S + \frac{1}{5} \delta_S^Q \delta_a^{[c_1} Z^{c_2 c_3 c_4]}{}_{MN}) \dots . \quad (2.4.14)$$

The  $+\dots$  in the above equations indicate the presence of generators which are of a higher level than we are considering in this paper.

The commutators of the generators of  $I_c(E_{11})$  subalgebra involving level  $\pm 2$  generators with those of the vector representation are given by

$$[S^{a_1 a_2}{}_P, P_b] = 2 \delta_b^{[a_1} Z^{a_2]}{}_P , \quad (2.4.15)$$

$$[S^{a_1 a_2}{}_P, Z^{RS}] = 2 \delta_P^{[R} Z^{a_1 a_2]S]} , \quad (2.4.16)$$

$$[S^{a_1 a_2}{}_P, Z^b{}_S] = 2 Z^{a_1 a_2 b}{}_P{}_S + 2 \delta_S^P \delta_{[a_1}^b P_{a_2]} , \quad (2.4.17)$$

$$[S^{a_1 a_2}{}_P, Z^{b_1 b_2 R}] = -2 \delta_P^R (Z^{a_1 a_2 b_1 b_2} + Z^{b_1 b_2 [a_1, a_2]}) - \frac{1}{2} Z^{a_1 a_2 b_1 b_2 R}{}_P - 2 \delta_{a_1 a_2}^{b_1 b_2} Z^{PR} , \quad (2.4.18)$$

$$[S_{a_1 a_2}{}^P, Z^{b_1 b_2 b_3}{}_{RS}] = -6 \delta_{a_1 a_2}^{[b_1 b_2]} \delta_{[R}^P Z^{b_3]}{}_{S]} + \dots \quad (2.4.19)$$

$$[S^{a_1 a_2}{}_L, Z^{b_1 \dots b_4}] = \frac{6}{5} \delta_{a_1 a_2}^{[b_1 b_2} Z^{b_3 b_4]L} + \dots , \quad (2.4.20)$$

$$[S^{a_1 a_2}{}_L, Z^{b_1 b_2 b_3, c}] = -3 (\delta_{a_1 a_2}^{[b_1 b_2} Z^{b_3]cL} + \delta_{a_1 a_2}^c Z^{b_2 b_3]L}) + \dots , \quad (2.4.21)$$

$$[S^{a_1 a_2}{}_L, Z^{b_1 \dots b_4 R}{}_S] = 8 \cdot 3 \delta_{a_1 a_2}^{[b_1 b_2]} (\delta_S^L Z^{b_3 b_4]R} - \frac{1}{5} \delta_S^R Z^{b_3 b_4]L}) + \dots . \quad (2.4.22)$$

The commutators of the generators of  $I_c(E_{11})$  subalgebra involving level  $\pm 3$  generators with those of the vector representation are given by

$$[S^{a_1 a_2 a_3 M}, P_b] = -6 \delta_b^{[a_1} Z^{a_2 a_3]M} , \quad (2.4.23)$$

$$[S^{a_1 a_2 a_3 M}, Z^{PQ}] = -2 \varepsilon^{MPQRS} Z^{a_1 a_2 a_3}{}_{RS} , \quad (2.4.24)$$

$$[S^{a_1 a_2 a_3 M}, Z^b{}_N] = Z^{a_1 a_2 a_3 b M}{}_N + 6 \delta_N^M Z^{b[a_1 a_2, a_3]} - 6 \delta_N^M Z^{a_1 a_2 a_3 b} , \quad (2.4.25)$$

$$[S^{a_1 a_2 a_3 M}, Z^{b_1 b_2 N}] = 12 \delta_M^N \delta_{[a_1 a_2}^{b_1 b_2} P_{a_3]} + \dots , \quad (2.4.26)$$

$$[S^{a_1 a_2 a_3 M}, Z^{b_1 b_2 b_3}{}_{NP}] = 3 \varepsilon_{MNPQR} \delta_{a_1 a_2 a_3}^{b_1 b_2 b_3} Z^{QR} + \dots , \quad (2.4.27)$$

$$[S^{a_1 a_2 a_3 M}, Z^{b_1 \dots b_4}] = \frac{3! \cdot 3!}{5} \delta_{a_1 a_2 a_3}^{[c_1 c_2 c_3} Z^{c_4]}{}_M + \dots , \quad (2.4.28)$$

$$[S^{a_1 a_2 a_3 M}, Z^{b_1 b_2 b_3, c}] = -9(\delta_{a_1 a_2 a_3}^{b_1 b_2 b_3} Z^c{}_M + \delta_{a_1 a_2 a_3}^{c[b_1 b_2} Z^{b_3]}{}_M) + \dots, \quad (2.4.29)$$

$$[S^{a_1 a_2 a_3 M}, Z^{b_1 \dots b_4 Q}{}_T] = -4 \cdot 4! (\delta_M^Q \delta_{a_1 a_2 a_3}^{[b_1 b_2 b_3} Z^{b_4]}{}_T - \frac{1}{5} \delta_T^Q \delta_{a_1 a_2 a_3}^{[b_1 b_2 b_3} Z^{b_4]}{}_M) + \dots. \quad (2.4.30)$$

The commutators of the generators of  $I_c(E_{11})$  subalgebra involving level  $\pm 4$  generators with those of the vector representation are given by

$$[S^{a_1 \dots a_4}{}_{MN}, P_b] = 8\delta_b^{[a_1} Z^{a_2 a_3 a_4]}{}_{MN}, \quad (2.4.31)$$

$$[S^{a_1 \dots a_4}{}_{MN}, Z^{PQ}] = 8\delta_{MN}^{PQ} Z^{a_1 \dots a_4} + 2\delta_{[M}^{[P} Z^{a_1 \dots a_4]Q]}{}_{N]} + \dots, \quad (2.4.32)$$

$$[S^{a_1 \dots a_4}{}_{S_1 S_2}, Z^{b_1 b_2 b_3}{}_{L_1 L_2}] = -4! \delta_{L_1 L_2}^{S_1 S_2} P_{[a_1} \delta_{a_2 a_3 a_4]}^{b_1 b_2 b_3} + \dots, \quad (2.4.33)$$

$$[S^{a_1 \dots a_4}{}_{S_1 S_2}, Z^{b_1 \dots b_4}] = -\frac{4!}{5} \delta_{a_1 \dots a_4}^{b_1 \dots b_4} Z^{S_1 S_2} + \dots, \quad (2.4.34)$$

$$[S^{a_1 \dots a_4}{}_{S_1 S_2}, Z^{b_1 b_2 b_3, c}] = 0 + \dots, \quad (2.4.35)$$

$$[S^{a_1 \dots a_4}{}_{S_1 S_2}, Z^{b_1 \dots b_4 R}{}_T] = 4 \cdot 4! \delta_{a_1 \dots a_4}^{b_1 \dots b_4} (\delta_T^{[S_1} Z^{S_2]R} + \frac{1}{5} \delta_T^R Z^{S_1 S_2}) + \dots. \quad (2.4.36)$$

Finally The commutators of the generators of  $I_c(E_{11})$  subalgebra involving level  $\pm 5$  generators with those of the vector representation are given by

$$[S^{a_1 \dots a_4, b}, P_c] = 8\delta_c^{[a_1} Z^{a_2 a_3 a_4], b} + 8(\delta_c^{[a_1} Z^{a_2 a_3 a_4]b} - \delta_c^b Z^{a_1 \dots a_4}), \quad (2.4.37)$$

$$[S^{a_1 \dots a_5 M}{}_N, P_c] = 5\delta_c^{[a_1} Z^{a_2 \dots a_5]M}{}_N, \quad (2.4.38)$$

$$[S^{a_1 \dots a_5 R}{}_S, Z^{b_1 \dots b_4}] = 0 + \dots, \quad (2.4.39)$$

$$[S^{a_1 \dots a_4, b}, Z^{b_1 \dots b_4}] = \frac{48}{5} (P_b \delta_{a_1 \dots a_4}^{b_1 \dots b_4} + P_{[a_1} \delta_{b|a_2 a_3 a_4]}^{b_1 \dots b_4}) + \dots, \quad (2.4.40)$$

$$[S^{a_1 \dots a_4, b}, Z^{c_1 c_2 c_3, d}] = -3! \cdot 3! (P_{[a_1} \delta_b^{[c_1} \delta_{|a_2 a_3 a_4]}^{c_2 c_3]d} + \delta_b^d P_{[a_1} \delta_{a_2 a_3 a_4]}^{c_1 c_2 c_3}) . \quad (2.4.41)$$

### 3 The Cartan forms

As explained in section one the non-linear realisation, and so the dynamics, is constructed from the Cartan forms. Given the  $E_{11} \otimes_s l_1$  algebra constructed previously in this paper these are easily found. We write the group element of  $E_{11} \otimes_s l_1$  in the form  $g = g_l g_E$  where

$$\begin{aligned} g_E = & \dots e^{A_{a_1 \dots a_5, b} P Q R^{a_1 \dots a_5, b} P Q} e^{A_{a_1 \dots a_6} (P Q) R^{a_1 \dots a_6} (P Q)} e^{A_{a_1 \dots a_6} P Q, R R^{a_1 \dots a_6} P Q, R} \\ & e^{h_{a_1 \dots a_4, b} R^{a_1 \dots a_4, b}} e^{\varphi_{a_1 \dots a_5 M} R^{a_1 \dots a_5 M}{}_N} e^{A_{a_1 \dots a_4} M N R^{a_1 \dots a_4} M N} \\ & e^{A_{a_1 a_2 a_3 M} R^{a_1 a_2 a_3 M}} e^{A_{a_1 a_2} M R^{a_1 a_2 M}} e^{A_{a M N} R^{a M N}} e^{\varphi_M{}^N R^M{}_N} e^{h_a{}^b K^a{}_b}, \end{aligned} \quad (3.1)$$

and

$$g_l = e^{x^a P_a} e^{x_{MN} Z^{MN}} e^{x_a{}^M Z^a{}_M} e^{x_{a_1 a_2} Z^{a_1 a_2}} e^{x_{a_1 a_2 a_3}{}^{MN} Z^{a_1 a_2 a_3}{}_{MN}} e^{x_{a_1 a_2 a_3, b} Z^{a_1 a_2 a_3, b}} e^{x_{a_1 \dots a_5} Z^{a_1 \dots a_5}} e^{x_{a_1 \dots a_4}{}^M Z^{a_1 \dots a_4}{}_M} e^{x_{a_1 \dots a_5}{}^M Z^{a_1 \dots a_5}{}_M} . \quad (3.2)$$

We note that the parameters of the group element  $g_E$  will be the fields of the theory while those of the group element  $g_l$  correspond to the generalised spacetime coordinates. The fields depend on the coordinates. In the above form of the group element we have gauged away the part of the  $E_{11}$  group element that depends on the negative level generators using the local  $I_c(E_{11})$  symmetry. This symmetry also contains the local Lorentz symmetry and we have not used this to make the graviton field symmetric. The analogous statement holds for the internal  $SO(1,4)$  symmetry.

The Cartan form of equation (1.5) can be written as

$$\begin{aligned} \mathcal{V} = & G_a{}^b K^a{}_b + G_M{}^N R^M{}_N + G_{aMN} R^{aMN} + G_{a_1 a_2}{}^M R^{a_1 a_2}{}_M \\ & + G_{a_1 a_2 a_3}{}^M R^{a_1 a_2 a_3}{}_M + G_{a_1 \dots a_4}{}^{MN} R^{a_1 \dots a_4}{}_{MN} \\ & + G_{a_1 \dots a_4, b} R^{a_1 \dots a_4, b} + G_{a_1 \dots a_5}{}^M R^{a_1 \dots a_5}{}_M + G_{a_1 \dots a_5, b} R^{a_1 \dots a_5, b} \\ & + G_{a_1 \dots a_6}{}^{(PQ)} R^{a_1 \dots a_6}{}_{(PQ)} + G_{a_1 \dots a_6}{}^{PQ, R} R^{a_1 \dots a_6}{}_{PQ, R} + \dots \end{aligned} \quad (3.3)$$

In this paper, we only need the Cartan forms up to level 6.

The explicit for of the  $G$ 's in terms of the fields of equation (3.1) up to level 4 are

$$\begin{aligned} G_a{}^b &= (e^{-1} de)_a{}^b , \\ G_M{}^N &= (f^{-1} df)_M{}^N , \\ G_{aMN} &= e_a{}^\mu f_M{}^{\dot{M}} f_N{}^{\dot{N}} dA_{\mu \dot{M} \dot{N}} , \\ G_{a_1 a_2}{}^M &= e_{a_1}{}^{\mu_1} e_{a_2}{}^{\mu_2} f_M{}^{\dot{M}} (dA_{\mu_1 \mu_2}{}^{\dot{M}} - \frac{1}{2} \varepsilon^{\dot{M} \dot{N} \dot{P} \dot{Q} \dot{R}} A_{[\mu_1 \dot{N} \dot{P}} dA_{\mu_2] \dot{Q} \dot{R}}) , \\ G_{a_1 a_2 a_3}{}^M &= e_{a_1}{}^{\mu_1} e_{a_2}{}^{\mu_2} e_{a_3}{}^{\mu_3} f_M{}^{\dot{M}} (dA_{\mu_1 \mu_2 \mu_3}{}^{\dot{M}} - A_{[\mu_1 \dot{N} \dot{M}} dA_{\mu_2 \mu_3]{}^{\dot{N}}} \\ &+ \frac{1}{3!} A_{[\mu_1 \dot{N} \dot{M}} A_{\mu_2 \dot{R} \dot{S}} dA_{\mu_3]{}^{\dot{P} \dot{Q} \dot{R} \dot{S}}} \varepsilon^{\dot{P} \dot{Q} \dot{R} \dot{S} \dot{N}}) , \\ G_{a_1 \dots a_4}{}^{MN} &= e_{a_1}{}^{\mu_1} \dots e_{a_4}{}^{\mu_4} f_M{}^{\dot{M}} f_N{}^{\dot{N}} (dA_{\mu_1 \dots \mu_4}{}^{\dot{M} \dot{N}} \\ &- \varepsilon^{\dot{M} \dot{N} \dot{P} \dot{Q} \dot{R}} A_{[\mu_1 \dot{P} \dot{Q}} dA_{\mu_2 \mu_3 \mu_4]{}^{\dot{R}}} - \frac{1}{2} \varepsilon^{\dot{M} \dot{N} \dot{P} \dot{Q} \dot{R}} A_{[\mu_1 \dot{P} \dot{Q}} A_{\mu_2 \dot{R} \dot{S}} dA_{\mu_3 \mu_4]{}^{\dot{S}}} \\ &- 5 A_{[\mu_1 \dot{P} \dot{Q}} A_{\mu_2}{}^{\dot{R} \dot{Q}} A_{\mu_3}{}^{\dot{P}} dA_{\mu_4]{}^{\dot{M} \dot{N}}) . \end{aligned} \quad (3.4)$$

where  $e_\mu{}^a = (e^h)_\mu{}^a$  and  $f_M{}^N = (e^\varphi)_M{}^N$ . The dotted latin indices  $\dot{M}, \dot{N}, \dots$  can be thought of as curved indices and the  $M, N, \dots$  indices as flat indices in the internal space. Indeed we can regard  $f_M{}^N$  as the analogue of usual vielbein  $e_\mu{}^a$  but in the internal space which has the local  $SO(1,4)$  symmetry.

We observe that for the gauge choice in the local  $I_c(E_{11})$  symmetry in which we are working the Cartan forms corresponding to negative level generators vanish, as was implicitly taken account of when we wrote equation (3.3).

#### 4 Transformations of the Cartan forms

To find the equations of motion we will need the transformations of the Cartan forms under the local transformations as in equation (1.4). We recall that these local transformations act on the Cartan forms as in equation (1.8) and that the Cartan forms are inert under the rigid  $E_{11} \otimes_s l_1$  transformations. The local transformation  $h \in I_c(E_{11})$  which involves the  $\pm 1$  generators of  $E_{11}$  is of the form

$$h = 1 - \Lambda_{aMN} S^{aMN}, \quad (4.1)$$

where  $S^{aMN} = R^{aMN} - R_{aMN}$ . If the equations of motion are invariant under these transformations and the local  $SO(1,4) \times SO(5)$  transformations at level zero then they are invariant under the full  $I_c(E_{11})$  transformations.

We find that under the above local transformation, the Cartan form transforms as

$$\delta \mathcal{V}_E = [\Lambda_{aMN} S^{aMN}, \mathcal{V}_E] - S^{aMN} d\Lambda_{aMN}, \quad (4.2)$$

Evaluating this equation using the algebra given in section three we find that the Cartan form transformations up to level 5, as

$$\delta G_a{}^b = 2\Lambda^{aMN} G_{bMN} - \frac{2}{5} \delta_b^a \Lambda^{cMN} G_{cMN}, \quad (4.3)$$

$$\delta G_M{}^N = 4\Lambda^{cPN} G_{cPM} - \frac{4}{5} \delta_M^N \Lambda^{cPQ} G_{cPQ} \quad (4.4)$$

$$\delta G_{aMN} = -\Lambda_{bMN} G_a{}^b - 2\Lambda_{aP[N} G_{M]}{}^P - \varepsilon_{MNPQR} \Lambda_{bQR} G_{ba}{}^P - d\Lambda_{aMN}, \quad (4.5)$$

$$\delta G_{a_1 a_2}{}^M = \varepsilon^{MNPQR} \Lambda_{[a_1 NP} G_{a_2]QR} + 12\Lambda^{bNM} G_{ba_1 a_2 N}, \quad (4.6)$$

$$\delta G_{a_1 a_2 a_3 M} = \Lambda_{[a_1 NM} G_{a_2 a_3]}{}^N - 2\varepsilon_{MPQRS} \Lambda_{bPQ} G_{ba_1 a_2 a_3}{}^{RS}, \quad (4.7)$$

$$\begin{aligned} \delta G_{a_1 \dots a_4}{}^{MN} &= \varepsilon^{MNPQR} \Lambda_{[a_1 PQ} G_{a_2 a_3 a_4]R} + 20\Lambda^{bP[N} G_{ba_1 \dots a_4 P]}{}^M \\ &\quad - 2\Lambda_{bMN} G_{a_1 \dots a_4, b}, \end{aligned} \quad (4.8)$$

$$\begin{aligned} \delta G_{a_1 \dots a_5 M}{}^N &= -2\Lambda_{[a_1 PM} G_{a_2 \dots a_5]}{}^{PN} + \frac{2}{5} \delta_M^N \Lambda_{[a_1 PQ} G_{a_2 \dots a_5]}{}^{PQ} \\ &\quad + \frac{2}{5} \Lambda^{dNP} G_{a_1 \dots a_5, dMP} - \frac{2}{25} \delta_M^N \Lambda^{dPQ} G_{a_1 \dots a_5, dPQ} \\ &\quad + 2\Lambda^{dPQ} \varepsilon_{PQRS} G_{da_1 \dots a_5}{}^{S(N,R)} + 3\Lambda^{dNP} G_{da_1 \dots a_5 (MP)}, \end{aligned} \quad (4.9)$$

$$\begin{aligned} \delta G_{a_1 \dots a_4, b} &= \frac{4}{5} \Lambda_{bMN} G_{a_1 \dots a_4}{}^{MN} - \frac{4}{5} \Lambda_{[a_1 MN} G_{a_2 \dots a_4]b}{}^{MN} \\ &\quad - \Lambda^{cMN} G_{ca_1 \dots a_4, bMN} + \Lambda^{cMN} G_{c[a_1 \dots a_4, b]MN}, \end{aligned} \quad (4.10)$$

$$\delta G_{a_1 \dots a_6}{}^{MN,P} = 2\varepsilon^{QRSMN} \Lambda_{[a_1 Q R} G_{a_2 \dots a_6] S}{}^P - 2\varepsilon^{QRS[MN} \Lambda_{[a_1 Q R} G_{a_2 \dots a_6] T}{}^P] + \dots, \quad (4.11)$$

$$\delta G_{a_1 \dots a_6(MN)} = 8\Lambda_{[a_1(N|P} G_{a_2 \dots a_6]|M)}{}^P + \dots, \quad (4.12)$$

$$\begin{aligned} \delta G_{a_1 \dots a_5, bMN} &= 20\Lambda_{b[N|P} G_{a_1 \dots a_5|M]}{}^P \\ &- 20\Lambda_{[b[N|P} G_{a_1 \dots a_5]|M]}{}^P + 10\Lambda_{[a_1 MN} G_{a_2 \dots a_5], b} + \dots \end{aligned} \quad (4.13)$$

where the  $\dots$  represent level 7 forms.

In fact the first term of equation (4.2) does not preserve our gauge choice as it contains terms which contain the level minus one generators. To correct for this we must compensate by choosing the second term in equation (4.2) so that we do preserve our gauge choice. In particular following the treatment of the eleven dimensional theory [7,8], we must require the condition

$$[\Lambda \cdot R^{(-1)}, \mathcal{V}^{(0)}] - d\Lambda \cdot R^{(-1)} = 0, \quad (4.14)$$

where the superscripts give the relevant level. This equation implies that the  $\Lambda^{aMN}$  must obey the equation

$$d\Lambda^{aMN} = G_b{}^a \Lambda^{bMN} + 2G_P{}^{[M} \Lambda^{a|P|N]}, \quad (4.15)$$

which is solved by

$$\Lambda_c{}^{\mu\dot{K}\dot{L}} e_\mu{}^a f_{\dot{K}}{}^M f_{\dot{L}}{}^N = \Lambda^{aMN}, \quad (4.16)$$

where the  $c$  subscript represents the fact that the  $\Lambda^{\mu\dot{K}\dot{L}}$  with curved indices is a constant. Substituting this condition back into the transformation of the level 1 Cartan form in equation (4.5) to find that

$$\delta G_{aMN} = -2\Lambda_{bMN} G_{(ba)} - 4\Lambda_{aP[N} G_{(M]P)} - \varepsilon_{MNPQR} \Lambda_{bQR} G_{ba}{}^P \quad (4.17)$$

We note at this point, that in the following calculations, we come across the derivative of this parameter  $\Lambda^{aMN}$ , and that using equation (4.16), we notice that only  $\Lambda^{\mu\dot{K}\dot{L}}$  with curved indices is independent of the generalised space-time coordinates.

So far we have written the Cartan forms as forms and so what we actually have written say in the last section is

$$G_{\underline{\alpha}} = dz^\Pi G_{\Pi, \underline{\alpha}}, \quad (4.18)$$

where the index  $\Pi$  represents the  $l_1$  representation, and index  $\underline{\alpha}$  is an  $E_{11}$  index. We notice that once the Cartan forms are written in this way, they are no longer invariant under the rigid transformations. We can correct this by changing the first index into a tangent index using the inverse vielbein

$$G_{A, \underline{\alpha}} = (E^{-1})_A{}^\Pi G_{\Pi, \underline{\alpha}}, \quad (4.19)$$

and then the Cartan forms with the local flat index are inert under the rigid transformations. We will refer to this first index as the  $l_1$  index.

We find, using equation (1.9), that the variation on the  $l_1$  tangent index under the above local transformation is given by

$$\delta G_{a, \alpha} = -2\Lambda_{aMN} G^{MN}{}_{, \alpha}, \quad (4.20)$$

$$\delta G^{MN}_{,\alpha} = \Lambda^{aMN} G_{a,\alpha} . \quad (4.21)$$

Of course the  $E_{11}$  index also transforms as in equations (4.3-4.13) and (4.17) and so the actual local  $I_c(E_{11})$  transformation of the above Cartan form is the sum of the terms in the two equations.

We conclude this section by making some observations that will be essential when calculating the equations of motion in the next section. Let us consider the transformation of the level one Cartan form  $G_{a_1, a_2 MN}$  of equation (4.17). Even we antisymmetrise the  $a_1$  and  $a_2$  indices we observe that the transformation contains Cartan forms that do not have their indices antisymmetrised in a similar way, that is, the indices involving the  $l_1$  index. We will find that the calculation of the equations of motion requires objects for which the indices are antisymmetrised. We will now show how to construct objects with this property by using the coordinates beyond those of spacetime which are in the vector representation. Such a level one object is given by

$$\mathcal{G}_{a_1 a_2 MN} = G_{[a_1, a_2] MN} + \varepsilon_{MNPQR} G^{QR}_{, a_1 a_2}{}^P , \quad (4.22)$$

which transforms as

$$\delta \mathcal{G}_{a_1 a_2 MN} = -2\Lambda^{bMN} G_{[a_1, (a_2] b]} - 4\Lambda_{[a_2 P [N} G_{a_1], (M] P]} - \frac{3}{2} \varepsilon_{MNPQR} \Lambda_{bQR} G_{[a_1, b a_2]}{}^P , \quad (4.23)$$

where we have kept only terms that involve derivatives with respect to the usual coordinates of spacetime. We observe that the right-hand side contains Cartan forms whose  $l_1$  index is antisymmetrised with its spacetime  $E_{11}$  indices.

The corresponding object at level two is given by

$$\mathcal{G}_{a_1 a_2 a_3}{}^M = G_{[a_1, a_2 a_3]}{}^M - 4G^{NM}_{, a_1 a_2 a_3 N} , \quad (4.24)$$

It has the local transformation

$$\delta \mathcal{G}_{a_1 a_2 a_3}{}^M = \varepsilon^{PQRS} \Lambda_{[a_2 PQ} G_{a_1, a_3] RS} + 16\Lambda_{bNM} G_{[a_1, b a_2 a_3] N} . \quad (4.25)$$

At level 3 we define the object

$$\mathcal{G}_{a_1 \dots a_4 M} = G_{[a_1, a_2 a_3 a_4] M} + \frac{1}{2} \varepsilon_{PQRS} G^{PQ}_{, a_1 a_2 a_3 a_4 RS} , \quad (4.26)$$

It has the transformation

$$\delta \mathcal{G}_{a_1 \dots a_4 M} = \Lambda_{[a_2 NM} G_{a_1, a_3 a_4]}{}^N - \frac{5}{2} \Lambda_{bPQ} \varepsilon_{PQRS} G_{[a_1, b a_2 a_3 a_4] RS} . \quad (4.27)$$

At level 4, we define

$$\mathcal{G}_{a_1 \dots a_5}{}^{MN} = G_{[a_1, \dots a_5]}{}^{MN} + 4G^{P[N}_{, a_1 \dots a_5 P}{}^{M]} , \quad (4.28)$$

which has the transformation

$$\begin{aligned} \delta \mathcal{G}_{a_1 \dots a_5}{}^{MN} &= \varepsilon_{PQRMN} \Lambda_{[a_2 PQ} G_{a_1, a_3 a_4 a_5] R} \\ &+ 24 \Lambda^{bP[N} G_{[a_1, b a_2 \dots a_5] P}{}^{M]} - 2 \Lambda_{bMN} G_{[a_1, \dots a_5], b} . \end{aligned} \quad (4.29)$$

At level 5, we define

$$\mathcal{G}_{[a_1, \dots a_6] M}{}^N = G_{[a_1, \dots a_6] M}{}^N - \frac{1}{3} \varepsilon_{PQ RSM} G^{PQ}{}_{, a_1 \dots a_6}{}^{S(N, R)} - \frac{1}{2} G^{NP}{}_{, a_1 \dots a_6 (MP)} , \quad (4.30)$$

and

$$\mathcal{G}_{[a_1, \dots a_5], b} = G_{[a_1, \dots a_5], b} + \frac{3}{25} G^{MN}{}_{, a_1 \dots a_5, bMN} , \quad (4.31)$$

which transform as

$$\begin{aligned} \delta G_{[a_1, \dots a_6] M}{}^N &= -2 \Lambda_{[a_2 PM} G_{a_1, a_3 \dots a_6]}{}^{PN} + \frac{2}{5} \delta_M^N \Lambda_{[a_2 PQ} G_{a_1, a_3 \dots a_6]}{}^{PQ} \\ &- \frac{2}{5} \Lambda^{dNP} G_{[a_1, \dots a_6], dMN} - \frac{2}{25} \delta_M^N \Lambda^{dPQ} G_{[a_1, \dots a_6], dPQ} \\ &+ \frac{7}{3} \Lambda^{dPQ} \varepsilon_{PQ RSM} G_{[a_1, d a_2 \dots a_6]}{}^{S(N, R)} + \frac{7}{2} \Lambda^{dNP} G_{[a_1, d a_2 \dots a_6] (MP)} , \end{aligned} \quad (4.32)$$

and

$$\begin{aligned} \delta G_{[a_1, \dots a_5], b} &= \frac{4}{5} \Lambda_{bMN} G_{[a_1, \dots a_5]}{}^{MN} - \frac{4}{5} \Lambda_{[a_2 MN} G_{a_1, a_3 a_4 a_5] b}{}^{MN} \\ &- \frac{6}{5} \Lambda^{cMN} G_{a_1, \dots a_5 c], bMN} + \frac{6}{25} G_{[a_1, \dots a_5, b], cMN} , \end{aligned} \quad (4.33)$$

Finally, at level 6, we find the transformations

$$\begin{aligned} \delta G_{[a_1, \dots a_7]}{}^{MN, P} &= 2 \varepsilon^{QRSMN} \Lambda_{[a_2 QR} G_{a_1, a_3 \dots a_7] S}{}^P \\ &- 2 \varepsilon^{QRS} [MN \Lambda_{[a_2 QR} G_{a_1, a_3 \dots a_7] S}{}^P] + \dots , \end{aligned} \quad (4.34)$$

$$\delta G_{[a_1, \dots a_7] (MN)} = 8 \Lambda_{[a_2 (N|P} G_{a_1, a_3 \dots a_7] |M)}{}^P + \dots , \quad (4.35)$$

$$\begin{aligned} \delta G_{[a_1, \dots a_6], bMN} &= \frac{50}{3} \Lambda_{b[N|P} G_{[a_1, \dots a_6] |M]}{}^P \\ &+ \frac{50}{3} \Lambda_{[a_2 [N|P} G_{a_1, a_3 \dots a_6] b |M]}{}^P + 16 \Lambda_{[a_2 MN} G_{a_1, a_3 \dots a_6], b} + \dots , \end{aligned} \quad (4.36)$$

where the  $\dots$  represent higher level Cartan forms. We note that we have not defined new  $l_1$  modified objects at level 6, as we are only concerned with the transformation into the lower level Cartan forms in this paper and these additions would involve level seven fields.

One can think about the above definition in terms of gauge symmetry which requires that the indices be antisymmetric. As a result one see that the extra coordinates beyond those of spacetime are required to ensure gauge symmetry. In the  $E_{11}$  approach we do not

require gauge symmetries only the symmetries of the non-linear realisation. It turns out that the results are indeed gauge invariant!

## 5 The equations of motion

We begin the calculation by finding duality relations for the form fields contained in the theory. We can expect that the one form is dual to the four form and if this were the case it would obey an equation of the form

$$D_{a_1 a_2 M N} \equiv \mathcal{G}_{a_1 a_2 M N} + e_2 \varepsilon_{a_1 a_2}{}^{b_1 \dots b_5} \mathcal{G}_{b_1 \dots b_5}{}^{M N} = 0 , \quad (5.1)$$

Similarly we may expect that the two form is dual to the three form and so this equation would be of the form

$$D_{a_1 a_2 a_3}{}^M \equiv \mathcal{G}_{a_1 a_2 a_3}{}^M + e_3 \varepsilon_{a_1 a_2 a_3}{}^{b_1 \dots b_4} \mathcal{G}_{b_1 \dots b_4}{}^M = 0 . \quad (5.2)$$

where  $e_2$  and  $e_3$  are constants. The equation are restricted to be of the form on the grounds of Lorentz symmetry. To see if the theory really does have these duality equation we must examine if they are invariant under the local  $I_c(E_{11})$  transformations of equations (4.3)-(4.13) and equation (4.17). One finds that the equations vary into each other under these transformations if the constants  $e_2$  and  $e_3$  take the values  $e_2 = \mp \frac{i}{2}$  and  $e_3 = \pm \frac{i}{3}$ . In the following, we choose to work with the first sign, i.e.  $e_2 = -\frac{i}{2}$  and  $e_3 = \frac{i}{3}$ , but one can easily recover where the sign changes for the other case (simply by changing the sign whenever a  $i$  appears). The precise transformations are

$$\delta D_{a_1 a_2 M N} = -\frac{3}{2} \varepsilon_{M N P Q R} \Lambda_{b Q R} D_{a_1 b a_2}{}^P + \dots , \quad (5.3)$$

$$\delta D_{a_1 a_2 a_3}{}^M = \varepsilon^{P Q R S M} \Lambda_{[a_2 P Q} D_{a_1 a_3] R S} + \frac{i}{3} \varepsilon_{a_1 a_2 a_3}{}^{b_1 \dots b_4} \Lambda_{b_2 N M} D_{b_1 b_3 b_4}{}^N . \quad (5.4)$$

where  $+\dots$  means the addition of terms involving the gravity and the scalars fields. As anticipated in section four the invariance of the equations requires the objects defined in that section that have totally antisymmetrised indices. Roughly speaking the equations contain objects with such indices and so their variations must also contain objects with such indices in order for a cancelation to take place. We could have started out with the usual Cartan forms but then we would have found that we needed to add terms which was equivalent to using the above objects. The fact that the duality relations are invariant up to scalar and gravity terms tells us that these are the correct equations. The scalar and gravity terms will be cancelled by terms in the variations that are the gravity and scalar equations of motion. We will return to the full variation of the duality conditions in a future paper.

We now proceed as was done in the [78], namely we will work with equations that are second order in derivatives and only contain the gravity field and the one and two form fields. To this end we take the derivatives of the equations (5.1) and (5.2) in such a way that the three form and four form field drop out respectively. In doing this we need to use the explicit forms of the Cartan forms given in section three. Carrying this out on  $\mathcal{D}$  of equation (5.1) we find the result



$$\begin{aligned}
& \partial_{\mu_1} (\det(e)^{\frac{1}{2}} G^{[\mu_1, \mu_2] \dot{M} \dot{N}}) + \frac{2}{3} G_{[\mu_1, \mu_3] \dot{Q} \dot{R}} G^{[\mu_1, \mu_2 \mu_3] \dot{P}} \varepsilon^{\dot{M} \dot{N} \dot{P} \dot{Q} \dot{R}} \\
& + \frac{i}{4} \varepsilon^{\mu_1 \mu_2 \nu_1 \dots \nu_5} G_{[\mu_1, \nu_2 \nu_3] \dot{M}} G^{[\nu_1, \nu_4 \nu_5] \dot{N}} = 0 ,
\end{aligned} \tag{5.5}$$

The equivalent operation on the duality relation of equation (5.2) leads to the equation

$$\partial_{\mu_1} (\det(e)^{\frac{1}{2}} G^{[\mu_1, \mu_2 \mu_3] \dot{P}}) - \frac{i}{3} \varepsilon^{\mu_1 \mu_2 \mu_3 \nu_1 \dots \nu_4} G_{[\mu_1, \nu_2] \dot{N} \dot{P}} G^{[\nu_1, \nu_3 \nu_4] \dot{N}} = 0 . \tag{5.6}$$

We notice that the factors of the  $\det(e)^{\frac{1}{2}}$  appear due to their appearance in the inverse vielbein, a feature that is also present in the equivalent eleven dimensional calculation [7,8].

In order to vary equations (5.5) and (5.6) we will need to rewrite them in terms of the Cartan forms of section three whose variation we found in section four. Essentially this means rewriting it in such a way that all the indices on the Cartan forms are tangent indices both for spacetime as well as internal indices. This procedure leads to the two equations

$$\begin{aligned}
E^{a_2 QR} &= \frac{1}{2} G_{a_1, d}^d G^{[a_1, a_2] QR} - G_{a_1, d}^{a_1} G^{[d, a_2] QR} \\
&- G_{a_1, d}^{a_2} G^{[a_1, d] QR} - 2 G_{a_1, P}^{[Q} G^{a_1, a_2] P] R} + \det(e)^{\frac{1}{2}} e_{a_1}^\mu \partial_\mu (G^{[a_1, a_2] QR}) \\
&+ \frac{2}{3} G_{[a_1, a_3] MN} G^{[a_1, a_2 a_3] P} \varepsilon^{MNPQR} \\
&+ \frac{i}{4} \varepsilon^{a_1 a_2 b_1 \dots b_5} G_{[a_1, b_2 b_3] \dot{Q}} G^{[b_1, b_4 b_5] \dot{R}} = 0 ,
\end{aligned} \tag{5.7}$$

and

$$\begin{aligned}
E^{a_2 a_3 M} &= \frac{1}{2} G_{a_1, d}^d G^{[a_1, a_2 a_3] M} - G_{a_1, d}^{a_1} G^{[d, a_2 a_3] M} \\
&- 2 G_{a_1, d}^{[a_2} G^{a_1, d] a_3] M} + G_{a_1, M}^P G^{[a_1, a_2 a_3] P} + \det(e)^{\frac{1}{2}} e_{a_1}^\mu \partial_\mu (G^{[a_1, a_2 a_3] M}) \\
&- \frac{i}{3} \varepsilon^{a_1 a_2 a_3 b_1 \dots b_4} G_{[a_1, a_2] NP} G^{[b_1, b_3 b_4] N} = 0 ,
\end{aligned} \tag{5.8}$$

Although we have derived the above equations from the duality relations that are first order in derivatives we can regard these last two equations as the starting point of our quest to find the equations of motion for the fields in terms of which the seven dimensional theory is usually written. We will now vary them under the  $I_c(E_{11})$  transformations and show that, together with some other equations of motion, they are invariant. In carrying out this calculation we have neglected all terms that contain derivatives with respect to the higher level coordinates for reasons we will explain shortly.

Let us suppose that in the variation of one of the equations of motion we have a term of the form

$$\Lambda^{dMN} G_{d, \alpha} f^\alpha_{MN} , \tag{5.9}$$

where  $f^\alpha_{MN}$  is any function of the fields and their derivatives. Then we can cancel such a term by adding to the equations of motion the term

$$-G^{MN}_{,\alpha} f^\alpha_{MN} , \quad (5.10)$$

We will call such terms  $l_1$  terms. We carry out our variations keeping only terms that contain derivatives with respect to the usual coordinates of spacetime. However, the last remark implies that to do this we must find the equations of motion up to the level that contains all terms that have the usual spacetime derivatives as well as terms that are first order in derivatives with respect to the level one coordinates, that is, the  $l_1$  terms. Even if we begin with an equation of motion, such as those in equations (5.7) and (5.8), we will find the  $l_1$  terms. However, we do not find the terms that contain derivatives with respect to coordinates of level two and above. We note that in finding the duality relations of equations (5.1) and (5.2) we did find the  $l_1$  terms. In this way of doing things we do not for example keep the variation of the term in equation (5.10) that contains derivative with respect to the level two coordinates.

We will now carry out the local  $I_c(E_{11})$  transformations of equation (5.7). If we vary the terms in the first two lines, we the result

$$\begin{aligned} & e_{a_2}{}^{\mu_2} \partial_{\mu_1} (\omega_{\tau, \mu_1 \mu_2} \det(e) - \det(e)^{\frac{1}{2}} G_{\tau, [\mu_1 \mu_2]}) \Lambda_{\tau QR} \\ & - 2\Lambda^{a_2 MN} G_{a_1, dMN} G_{[a_1, d]}^{QR} - 8\Lambda^{cP[Q]G_{a_1, cPM} G_{[a_1, a_2]}^{M|R]} \\ & - 2\Lambda^{a_1 MN} G_{a_1, dMN} G_{[d, a_2]}^{QR} + 2\Lambda^{dMN} G_{a_1, dMN} G_{[a_1, a_2]}^{QR} , \end{aligned} \quad (5.11)$$

where

$$\det(e)^{\frac{1}{2}} w_{c, ab} = -G_{a, (bc)} + G_{b, (ac)} + G_{c, [ab]} . \quad (5.12)$$

We note that the terms on the second line and also the last term will be cancelled with terms from the transformation of the final terms in equation (5.7). We also notice that the second and the fifth terms are terms of the form given in equation (5.9), and so we can cancel them by adding corresponding  $l_1$  terms. Finally, we can manipulate the first term in the following way. We notice that

$$\begin{aligned} & e_\mu{}^a \partial_\nu (\det(e) \omega_{\tau,}{}^{\nu\mu}) = \\ & \det(e) (e_b{}^\nu \partial_\nu \omega_{\tau,}{}^{ba} + (e_\mu{}^a \partial_\nu e_c{}^\mu) \omega_{\tau,}{}^{\nu c} + (e_c{}^\lambda \partial_\nu e_\lambda{}^c) \omega_{\tau,}{}^{\nu a} + \partial_\nu e_b{}^\nu \omega_{\tau,}{}^{ba}) \end{aligned} \quad (5.13)$$

The first term will turn out to just what we will need. While the second term we can be rewritten as

$$e_b{}^\lambda \partial_\nu e_\lambda{}^a \omega_{\mu,}{}^{\nu b} = G_{c, \nu a} \omega_{\mu,}{}^{c\nu} = (-G_{a, (c\nu)} + G_{c, (a\nu)} + G_{\nu, [ac]}) \omega_{\mu,}{}^{c\nu} = \omega_{\nu,}{}^a{}_c \omega_{\mu,}{}^{c\nu} , \quad (5.14)$$

and the final two terms in (5.13) can be written as

$$\omega_{\mu,}{}^{ab} \partial_\lambda (\det(e) e_b{}^\lambda) = -\det(e) \omega_{\mu,}{}^{ab} \omega_{\lambda,}{}^{b\lambda} . \quad (5.15)$$

We note that the Ricci tensor is given by

$$R_{\mu}{}^a = \partial_{\mu}\omega_{\nu,}{}^{ab}e_b{}^{\nu} - \partial_{\nu}\omega_{\mu,}{}^{ab}e_b{}^{\nu} + \omega_{\mu,}{}^a{}_c\omega_{\nu,}{}^{cb}e_b{}^{\nu} - \omega_{\nu,}{}^a{}_c\omega_{\mu,}{}^{cb}e_b{}^{\nu} , \quad (5.16)$$

and so in equation (5.13) we find the expression

$$\det(e)(R_{\tau}{}^{a_2} - \partial_{\tau}(\omega_{\nu,}{}^{a_2 b})e_b{}^{\nu})\Lambda^{\tau QR} , \quad (5.17)$$

and again the second term in this is an  $l_1$  term of the form of equation (5.9).

Including  $l_1$  terms, we find that the equation of motion for the one form is

$$\begin{aligned} \mathcal{E}^{a_2 QR} &\equiv \frac{1}{2}G_{a_1, d}{}^d G_{[a_1, a_2]}{}^{QR} - G_{a_1, d}{}^{a_1} G_{[d, a_2]}{}^{QR} \\ &- G_{a_1, d}{}^{a_2} G_{[a_1, d]}{}^{QR} - 2G_{a_1, P}{}^{[Q} G_{[a_1, a_2]}{}^{P|R]} + \det(e)^{\frac{1}{2}} e_{a_1}{}^{\mu} \partial_{\mu} (G_{[a_1, a_2]}{}^{QR}) \\ &+ \frac{3}{2} G_{[a_1, a_3]MN} G_{[a_1, a_2 a_3]P} \varepsilon^{MNPQR} + \frac{i}{4} \varepsilon^{a_1 a_2 b_1 \dots b_5} G_{[a_1, b_2 b_3]}{}^{[Q} G_{[b_1, b_4 b_5]}{}^{R]} \\ &+ 8G^{P[Q}{}_{, a_1 P M} G_{[a_1, a_2]}{}^{M|R]} + e_{a_2}{}^{\mu_2} \partial_{\mu_1} (\det(e)^{\frac{1}{2}} G^{QR}{}_{, [\mu_1 \mu_2]}) \\ &+ \det(e) \partial^{QR} (\omega_{\nu,}{}^{a_2 b}) e_b{}^{\nu} - (\det(e)^{\frac{1}{2}} \partial^{P[R} (G_{a_2, |Q]}{}^P + G_{a_2, P}{}^{[Q]}) \\ &+ \frac{1}{2} (G_{a_2, |Q]}{}^P + G_{a_2, P}{}^{[Q]}) G^{P[R}{}_{, d}{}^{d} \\ &- (G_{a_2, N}{}^P + G_{a_2, P}{}^N) G^{P[R}{}_{, N}{}^{[Q]} + (G_{a_2, |Q]}{}^N + G_{a_2, N}{}^{[Q]}) G^{P[R}{}_{, P}{}^{N} \\ &+ (G_{d, |Q]}{}^P + G_{d, P}{}^{[Q]}) G^{P[R}{}_{, d}{}^{a_2}) = 0 . \end{aligned} \quad (5.18)$$

Using the same reasoning, we also find that the equation of motion for the two form is

$$\begin{aligned} \mathcal{E}^{a_2 a_3 M} &\equiv \frac{1}{2} G_{a_1, d}{}^d G^{[a_1, a_2 a_3]M} - G_{a_1, d}{}^{a_1} G^{[d, a_2 a_3]M} \\ &- 2G_{a_1, d}{}^{[a_2 |} G^{[a_1, d | a_3]]M} + G_{a_1, M}{}^P G_{[a_1, \dots a_3]P} + \det(e)^{\frac{1}{2}} e_{a_1}{}^{\mu} \partial_{\mu} (G^{[a_1, a_2 a_3]M}) \\ &- \frac{i}{3} \varepsilon^{a_1 \dots a_3 b_1 \dots b_4} (G_{[a_1, b_2]NM} G_{[b_1, b_3 b_4]}{}^N) \\ &+ \frac{1}{3} \varepsilon^{PQRS} \left( \frac{1}{2} G^{PQ}{}_{, d}{}^d G_{[a_2, a_3]RS} - 2G^{PQ}{}_{, d}{}^{[a_2 |} G^{[d, | a_3]]RS} + \det(e)^{\frac{1}{2}} \partial^{PQ} (G_{[a_2, a_3]RS}) \right) \\ &- \frac{2}{3} G^{QR}{}_{, S}{}^{[P} G_{[a_2, a_3]}{}^{S|T]} \varepsilon^{TMPQR} + 2G^{PQ}{}_{, dPQ} G_{[d, a_2 a_3]M} - 4G^{NP}{}_{, a_1 NM} G_{[a_1, a_2 a_3]P} = 0 . \end{aligned} \quad (5.19)$$

The transformation of the one form equation of motion is given by

$$\delta \mathcal{E}^{a_2 QR} = -\frac{3}{2} \Lambda_{cMN} \varepsilon^{MNPQR} \mathcal{E}^{ca_2}{}_P + \Lambda^{bQR} E_b{}^{a_2} + \Lambda_{a_2 P[Q} \mathcal{E}_{|R]P}$$

$$-\frac{i}{2}\varepsilon^{a_1 a_2 b_1 \dots b_5} \varepsilon^{MNPQR} G_{[a_1, b_2]MN} \Lambda_{[b_3 TP D_{b_1, b_4 b_5}]^T} + 4! \Lambda_{[a_4}^{P[R} \mathcal{D}_{a_1 a_2 a_3]P} G_{[a_1, a_3 a_4]}^{Q]} , \quad (5.20)$$

where  $E_a{}^b$  is

$$\begin{aligned} E_a{}^b &= \det(e) R_a{}^b - G_{a,(MN)} G_{b,(MN)} \\ &\quad - 2(2G_{[c,a]}^{MN} G_{[c,b]MN} - \frac{1}{5} \delta_a^b G_{[c_1, c_2]}^{MN} G_{[c_1, c_2]MN}) \\ &\quad - 3(3G_{[c_1, ac_2]}^{MN} G_{[c_1, bc_2]MN} - \frac{2}{5} \delta_a^b G_{[c_1, \dots c_3]}^P G_{[c_1, \dots c_3]P}) , \end{aligned} \quad (5.21)$$

and  $\mathcal{E}_{(QR)}$  by

$$\begin{aligned} \mathcal{E}_{(QR)} &= \frac{1}{2} G_{a_1, d}{}^d (G_{a_1, Q}^R + G_{a_1, R}^Q) - G_{a_1, d}{}^{a_1} (G_{d, Q}^R + G_{d, R}^Q) \\ &\quad G_{a_1, Q}^N G_{a_1, R}^N - G_{a_1, N}^Q G_{a_1, N}^R + \det e^{\frac{1}{2}} e_{a_1}{}^\mu \partial_\mu (G_{a_1, Q}^R + G_{a_1, R}^Q) \\ &\quad + 8(G_{[c_1, c_2]QP} G_{[c_1, c_2]RP} + \frac{1}{5} \delta_R^Q G_{[c_1, c_2]}^{NP} G_{[c_1, c_2]NP}) \\ &\quad - 6(G_{[c_1, \dots c_3]Q} G_{[c_1, \dots c_3]R} + \frac{1}{5} \delta_R^Q G_{[c_1, \dots c_3]}^P G_{[c_1, \dots c_3]P}) . \end{aligned} \quad (5.22)$$

Since the variation vanishes we find that  $E_a{}^b = 0$  and  $\mathcal{E}_{(QR)} = 0$ . We recognise these as the gravity and scalar equations of motion.

The transformation of the equation of motion for the two form is

$$\begin{aligned} \delta \mathcal{E}^{a_2 a_3 M} &= \frac{2}{3} \Lambda^{[a_2 PQ} E^{a_3]RS} \varepsilon_{PQ RSM} \\ &\quad + \frac{i}{3} \Lambda_{cNM} \left( \frac{1}{2} G_{a_1, d}{}^d \varepsilon^{a_1 c a_2 a_3 d_1 d_2 d_3} - G_{a_1, d}{}^{a_1} \varepsilon^{d c a_2 a_3 d_1 d_2 d_3} \right. \\ &\quad \left. - 2G_{a_1, d}{}^{[a_2 |} \varepsilon^{a_1 c d | a_3] d_1 d_2 d_3} \right) D_{d_1 d_2 d_3}{}^N \\ &\quad + \frac{i}{3} \varepsilon^{a_1 c a_2 a_3 d_1 d_2 d_3} \det(e)^{\frac{1}{2}} e_{a_1}{}^\mu \partial_\mu (\Lambda_{cNM} D_{d_1 d_2 d_3}{}^N) . \end{aligned} \quad (5.23)$$

Our final task is to vary the gravity and scalar equations of motion that we have just found. We begin with the gravity equation (5.21). The first step is to carry out the procedure similar to that at the end of section four but now we do it for the spin connection. Namely we add terms to the spin connection such that its variation under  $I_c(E_{11})$  leads to terms in which the  $l_1$  and  $E_{11}$  indices on the Cartan forms are antisymmetrised. this is achieved by the object

$$\det(e)^{\frac{1}{2}} \Omega_{c, ab} \equiv \det(e)^{\frac{1}{2}} \omega_{c, ab} - \frac{2}{5} \delta_c^b G^{MN}{}_{, aMN} + \frac{2}{5} \delta_c^a G^{MN}{}_{, bMN} , \quad (5.24)$$

whose transformation is given by

$$\delta(\det(e)^{\frac{1}{2}} \Omega_{c, ab}) = -2\Lambda^{cMN} G_{[a, b]MN} - 2\Lambda^{bMN} G_{[a, c]MN} + 2\Lambda^{aMN} G_{[b, c]MN}$$

$$+\frac{4}{5}\delta_c^b\Lambda^{dMN}G_{[a,d]MN}-\frac{4}{5}\delta_c^a\Lambda^{dMN}G_{[b,d]MN}. \quad (5.25)$$

We then replace  $\omega$  with  $\Omega$  in  $R_a{}^b$  to find

$$\mathcal{R}_a{}^b = \partial_\mu \Omega_\nu{}^{ab} e_b{}^\nu - \partial_\nu \Omega_\mu{}^{ab} e_b{}^\nu + \Omega_\mu{}^a{}_\nu \Omega_\nu{}^{cb} e_b{}^\nu - \Omega_\nu{}^a{}_\mu \Omega_\mu{}^{cb} e_b{}^\nu. \quad (5.26)$$

As explained above when we vary the gravity equation of motion we also find the terms in this equation of motion that are first order in derivatives with respect to the level one coordinates, the  $l_1$  terms. The result is given by

$$\begin{aligned} \mathcal{E}_a{}^b &\equiv \det(e)\mathcal{R}_a{}^b - G_{a,(MN)}G_{b,(MN)} \\ &-2(2G_{[c,a]}{}^{MN}G_{[c,b]MN} - \frac{1}{5}\delta_a^b G_{[c_1,c_2]}{}^{MN}G_{[c_1,c_2]MN}) \\ &-3(3G_{[c_1,ac_2]}{}^{MN}G_{[c_1,bc_2]MN} - \frac{2}{5}\delta_a^b G_{[c_1,\dots,c_3]}{}^P G_{[c_1,\dots,c_3]P}) \\ &-2\partial^{MN}G_{[b,a]MN} - 4G^{NP}{}_{,P}{}^M G_{[b,a]MN} - \frac{2}{5}G^{MN}{}_{,aMN}\omega_d{}^{bd} + \frac{2}{5}G^{MN}{}_{,dMN}\omega_a{}^{bd} \\ &+2G^{MN}{}_{,b}{}^c G_{[c,a]MN} + 2G^{MN}{}_{,a}{}^c G_{[c,b]MN} \\ &-4G_{b,(MP)}G^{PN}{}_{,aMN} - 4G_{a,(MP)}G^{PN}{}_{,bMN} = 0. \end{aligned} \quad (5.27)$$

Although the  $\mathcal{R}_a{}^b$  we introduced in equation (5.26) is not symmetric in  $a$  and  $b$  one can verify that  $\mathcal{E}_a{}^b$  is symmetric in  $a$  and  $b$  including the  $l_1$  terms that it contains.

The transformation of  $\mathcal{E}_a{}^b$  is given by

$$\begin{aligned} \delta\mathcal{E}_a{}^b &= -2\Lambda_{aMN}E^{bMN} - 2\Lambda^{bMN}E_{aMN} + \frac{4}{5}\delta_a^b\Lambda_{cMN}E^{cMN} \\ &-3i\Lambda_{dNP}\varepsilon_{c_1dac_2d_1d_2d_3}G_{[c_1,bc_2]}{}^P D_{d_1d_2d_3}{}^N \\ &-3i\Lambda_{dNP}\varepsilon_{c_1dbc_2d_1d_2d_3}G_{[c_1,ac_2]}{}^P D_{d_1d_2d_3}{}^N \\ &+\frac{6i}{5}\delta_a^b\Lambda_{dNP}\varepsilon_{c_1dc_2c_3d_1d_2d_3}G_{[c_1,c_2c_3]}{}^P D_{d_1d_2d_3}{}^N. \end{aligned} \quad (5.28)$$

Similarly we can find the transformation of the scalar equation of equation (5.22). We find that the equation of motion becomes

$$\begin{aligned} \mathcal{E}_{(QR)} &\equiv \frac{1}{2}G_{a_1,d}{}^d(G_{a_1,Q}{}^R + G_{a_1,R}{}^Q) - G_{a_1,d}{}^{a_1}(G_{d,Q}{}^R + G_{d,Q}{}^R) \\ &G_{a_1,Q}{}^N G_{a_1,R}{}^N - G_{a_1,N}{}^Q G_{a_1,N}{}^R + \det e^{\frac{1}{2}} e_{a_1}{}^\mu \partial_\mu (G_{a_1,Q}{}^R + G_{a_1,R}{}^Q) \\ &+8(G_{[c_1,c_2]QP}G_{[c_1,c_2]RP} + \frac{1}{5}\delta_R^Q G_{[c_1,c_2]}{}^{NP}G_{[c_1,c_2]NP}) \end{aligned}$$

$$\begin{aligned}
& -6(G_{[c_1, \dots, c_3]Q} G_{[c_1, \dots, c_3]R} + \frac{1}{5} \delta_R^Q G_{[c_1, \dots, c_3]P} G_{[c_1, \dots, c_3]P}) \\
& - \frac{8}{5} \delta_Q^R \partial_\mu (\det(e)^{\frac{1}{2}} G^{PN}{}_{,\mu PN}) \\
& - 2G_{a_1, d}{}^d G^{PR}{}_{, a_1 PQ} + G^{MN}{}_{, dMN} G_{d, Q}{}^R + G_{a_1, d}{}^{a_1} G^{PR}{}_{, dPQ} \\
& - 4G_{a_1, R}{}^N G^{PN}{}_{, a_1 PQ} + 4G_{a_1, N}{}^Q G^{PR}{}_{, a_1 PN} - 4 \det(e)^{\frac{1}{2}} e_{a_1}{}^\mu \partial_\mu (G^{PR}{}_{, a_1 QN}) \\
& - 2G_{a_1, d}{}^d G^{PQ}{}_{, a_1 PR} + G^{MN}{}_{, dMN} G_{d, R}{}^Q + G_{a_1, d}{}^{a_1} G^{PQ}{}_{, dPR} \\
& - 4G_{a_1, Q}{}^N G^{PN}{}_{, a_1 PR} + 4G_{a_1, N}{}^R G^{PQ}{}_{, a_1 PN} - 4 \det(e)^{\frac{1}{2}} e_{a_1}{}^\mu \partial_\mu (G^{PQ}{}_{, a_1 RN}) = 0, \quad (5.29)
\end{aligned}$$

and its transformation is given by

$$\begin{aligned}
\delta \mathcal{E}_{(QR)} & \rightarrow 8\Lambda_{cPR} E_{cPQ} + 8\Lambda_{cPQ} E_{cPR} - \frac{16}{5} \delta_{QR} \Lambda_{cPN} E^{cPN} \\
& + 2i\Lambda_{dPR} \varepsilon^{dd_1 d_2 d_3 c_1 c_2 c_3} G_{[c_1, c_2 c_3]Q} D_{d_1 d_2 d_3}{}^P \\
& + 2i\Lambda_{dPQ} \varepsilon^{dd_1 d_2 d_3 c_1 c_2 c_3} G_{[c_1, c_2 c_3]R} D_{d_1 d_2 d_3}{}^P \\
& - \frac{4i}{5} \delta_Q^R \Lambda_{dPN} \varepsilon^{dd_1 d_2 d_3 c_1 c_2 c_3} G_{[c_1, c_2 c_3]N} D_{d_1 d_2 d_3}{}^P. \quad (5.30)
\end{aligned}$$

Using the symmetries of the non-linear realisation we have found a set of equations that transform into each other. These are the equations of motion for the graviton (5.27), scalar (5.29), one form (5.18), and two form (5.19) in seven dimensions. If we truncate the equations so that they only contain derivatives with respect to the usual coordinates of spacetime then these equations are those of seven dimensional maximal supergravity as found in reference [14], once we discard terms with derivatives with respect to the level 1 generalised coordinates.

## 6 First order duality relations

In this section we will derive the duality relations which are first order in derivatives and also find their variations. In addition to those we discussed in section five we will find the duality relations that relate the graviton to the dual graviton and the scalar fields to the dual scalar fields. We begin by recalling, from section five, the transformation of the duality relation which relates the two form to the three form and had the form

$$D_{a_1 a_2 a_3}{}^M \equiv \mathcal{G}_{a_1 a_2 a_3}{}^M + \frac{i}{3} \varepsilon_{a_1 a_2 a_3}{}^{b_1 \dots b_4} \mathcal{G}_{b_1 \dots b_4 M} = 0, \quad (6.1)$$

and whose variation was given by

$$\delta D_{a_1 a_2 a_3 M} = \varepsilon^{PQRS} \Lambda_{[a_2 PQ} D_{a_1 a_3] RS} + \frac{i}{3} \varepsilon_{a_1 a_2 a_3}{}^{b_1 \dots b_4} \Lambda_{b_2 NM} D_{b_1 b_3 b_4}{}^N. \quad (6.2)$$

We observe that it transforms into itself and the 1-form duality relation.

In section five, we also transformed the duality relation which relates the one form to the four form but we did not include the terms in the variation that contained the scalar fields, graviton or their dual fields which have five spacetime indices and so are at level five. Carrying out the variation of this duality relation including these additional terms gives the result

$$\begin{aligned} \delta \mathcal{D}_{a_1 a_2 M N} = & -\Lambda_{[a_2 P [N D_{a_1], (M) P]} + \Lambda_{a M N} D_{b, [a_1 a_2]} - \Lambda^{b M N} D_{b, [a_1 a_2]} \\ & - \frac{3}{2} \varepsilon_{M N P Q R} \Lambda_{b Q R} D_{a_1 b a_2}{}^P + 4i \Lambda_{[a_2 P [N | \varepsilon_{a_1]}^{b_1 \dots b_6} \mathcal{G}_{b_1, b_2 \dots b_6 [P | M]]} \end{aligned} \quad (6.3)$$

where

$$D_{b, [a_1 a_2]} \equiv \omega_{b, a_1 a_2} \det(e)^{\frac{1}{2}} + i \varepsilon_{a_1 a_2}^{b_1 \dots b_5} \mathcal{G}_{[b_1, \dots b_5], b} , \quad (6.4)$$

$$D_{a, (M N)} \equiv 2G_{a, (M N)} - 4i \varepsilon_a^{b_1 \dots b_6} \mathcal{G}_{b_1, \dots b_6 (M N)} . \quad (6.5)$$

and

$$\mathcal{D}_{a_1 a_2 M N} \equiv \mathcal{G}_{a_1 a_2 M N} - \frac{i}{2} \varepsilon_{a_1 a_2}^{b_1 \dots b_5} \mathcal{G}_{b_1 \dots b_5}{}^{M N} + G^{M N}{}_{, [a_1 a_2]} = 0 . \quad (6.6)$$

When carrying out the variation to include the extra terms we find that the duality relation of equation (5.1) becomes modified by an  $l_1$  term following the procedure explained earlier in this paper.

As  $D_{a_1 a_2 M N} = 0$ , its variation under  $I_c(E_{11})$  implies that

$$D_{b, [a_1 a_2]} \doteq 0 , \quad D_{a, (M N)} = 0 , \quad (6.7)$$

which are the the duality relation of the scalar field and the graviton respectively, as well as the equation

$$G_{[a_1, a_2 \dots a_6] [M N]} \doteq 0 . \quad (6.8)$$

The dots above the equal signs signify that the equations only hold modulo certain local symmetries as explained in references [15, 8, 16, 17]. Equation (6.8) sets the field strength for the dual scalar field  $A_{a_1 \dots a_5 [M N]}$  to be zero and so this field is pure gauge and can be removed by the gauge transformation that exists at this level.

We now transform the new duality relations we have found in equation (6.7) using the variation given in section four. Varying the scalar field duality relations of equation (6.5) we find the result

$$\delta \mathcal{D}_{a, (M N)} = 8\Lambda_{c P N} D^{a c P M} + 8\Lambda_{c P M} D^{a c P N} - \frac{16}{5} \delta_N^M \Lambda_{c P Q} D^{a c P Q} + \dots \quad (6.9)$$

While the variation of the gravity duality relation is given by

$$\begin{aligned} \delta \mathcal{D}_{b, [a_1 a_2]} = & -2\Lambda^{b M N} D_{a_1 a_2 M N} + \frac{4}{5} \Lambda^{d M N} \delta_{[a_2}^b D_{a_1] d M N} \\ & + \frac{4}{6!5} \Lambda^{d M N} \delta_{[a_2}^b \varepsilon_{a_1]}^{d_1 \dots d_6} D_{d_1 \dots d_6, d M N} \end{aligned}$$

$$-\frac{4}{6!}\Lambda_{[a_2MN}\varepsilon_{a_1]}^{d_1\dots d_6}D_{d_1\dots d_6,bMN}+\partial_b\tilde{\Lambda}_{a_1a_2}, \quad (6.10)$$

where

$$D_{a_1\dots a_6,bMN}\equiv 2(3!)^2iG_{[a_1,\dots a_6],bMN}+\varepsilon_{a_1\dots a_6}{}^d\mathcal{G}_{[d,b]MN}=0, \quad (6.11)$$

and

$$\partial_b\tilde{\Lambda}_{a_1a_2}=-\frac{i}{25}\varepsilon_{a_1a_2}{}^{b_1\dots b_5}(\Lambda_{b_1MN}\mathcal{G}_{b,b_2\dots b_5}{}^{MN}+\Lambda^{cMN}G_{b,b_1\dots b_5,cMN}). \quad (6.12)$$

In equation (6.11) we have a new duality relation which involves a level six field. This term is analogous to the duality relation connecting the  $A_{a_1a_2a_3}$  field to the  $A_{b_1\dots b_9,a_1a_2a_3}$  in eleven dimensions as discussed in reference [16]. In equation (6.12) we find the Lorentz transformations which should be expected as we are varying a duality relation that only holds modulo Lorentz transformations, also like the situation in reference [15].

When transforming the scalar and graviton duality relations we find they are modified by  $l_1$  terms. Including these terms the duality relations used in the variation are

$$\mathcal{D}_{b,[a_1a_2]}\equiv\Omega_{b,[a_1a_2]}\det(e)^{\frac{1}{2}}+i\varepsilon_{a_1a_2}{}^{b_1\dots b_5}\mathcal{G}_{[b_1,\dots b_5],b}, \quad (6.13)$$

and

$$\mathcal{D}_{a,(MN)}\equiv 2G_{a,(MN)}-4i\varepsilon_a{}^{b_1\dots b_6}\mathcal{G}_{b_1,\dots b_6(MN)}-4G^{PN}{}_{,aPM}-4G^{PM}{}_{,aPN}+\frac{4}{5}\delta_N^MG^{PQ}{}_{,aPQ}, \quad (6.14)$$

In the first relation we have replaced  $\omega_{b,[a_1a_2]}$  by  $\Omega_{b,[a_1a_2]}$  which includes the required  $l_1$  terms as we did in equation (5.24).

The factors of  $i$  that appear in the above relations can be removed from all the equations in this paper by some field redefinitions. We take the parameter  $\Lambda_{aNM}\rightarrow i\Lambda_{aNM}$ , change the fields with an odd number of Lorentz indices by a factor of  $i$ , leave the fields with an even number of indices the same and finally put a factor of  $i$  with  $\partial^{MN}$ .

In this section we have found that the fields up to level five satisfy duality relations that are first order in derivatives vary under  $I_c(E_{11})$  into themselves as well as relations involving level six fields. It would be interesting to carry out the calculation to determine the later duality relations which involve the fields responsible for the gauged seven dimensional supergravities. It would also be interesting to derive all the second order equations of motion of section five from the first order duality relation as was done in eleven dimensions in [17]. However, as was spelt out there this is a subtle procedure as one must correctly take account of the fact that some of these relations hold modulo certain transformations.

## 7 Conclusion

In this paper we have constructed, at low levels, the non-linear realisation of the semi-direct product of  $E_{11}$  with its vector representation in seven dimensions. The resulting dynamical equations follow essentially uniquely from the  $E_{11}$  Dynkin diagram once we delete node seven and take the corresponding decomposition. These equations agree with those of seven dimensional supergravity if only keep the fields used in the usual description of seven dimensional supergravity as well as keep only derivatives with respect to the



usual spacetime coordinates. It has been proposed that one can, by taking different decompositions of  $E_{11}$ , find all the massless maximal supergravities from the the non-linear realisation of the semi-direct product of  $E_{11}$  with its vector representation by taking the different decompositions. It is good to see how this works in detail in seven dimensions in this paper.

Systematically extending this calculation to level six we will find the dynamics for the six form gauge fields and it would be good to examine in detail how these lead to all the gauged supergravities in seven dimensions as indeed it did in ten dimensions [16]. We hope to carry out this calculation in a future paper.

## Appendix A The generators of $E_{11}$ decomposed into representations of $I_c(E_{11})$

The  $E_{11}$  algebra can be split into those that are even under the action of the Cartan involution and those that are odd. The former are by definition the algebra  $I_c(E_{11})$  and the latter belong to a representation of  $I_c(E_{11})$ , their commutators belong to  $I_c(E_{11})$  and they are given by

$$\begin{aligned} T^a{}_b &= R^a{}_b + R^b{}_a, \quad ; \quad T^M{}_N = R^M{}_N + R^N{}_M, \quad ; \quad T^{aMN} = R^{aMN} + R_{aMN}, \\ T^{a_1 a_2}{}_M &= R^{a_1 a_2}{}_M - R_{a_1 a_2}{}^M, \quad ; \quad T^{a_1 a_2 a_3 M} = R^{a_1 a_2 a_3 M} + R_{a_1 a_2 a_3 M}, \quad ; \quad \dots \end{aligned} \quad (A.1)$$

In this appendix we compute the commutators between these generators. Firstly, the commutators of the level 0 generators are given by

$$[T^a{}_b, T^c{}_d] = \delta_b^c J^a{}_d + \delta_a^c J^b{}_d - \delta_a^d J^c{}_b - \delta_b^d J^c{}_a, \quad (A.2)$$

$$[T^M{}_N, T^P{}_Q] = \delta_N^P S^M{}_Q + \delta_M^P S^N{}_Q - \delta_Q^M S^P{}_N - \delta_Q^N S^P{}_M, \quad (A.3)$$

$$[T^a{}_b, T^M{}_N] = 0. \quad (A.4)$$

Then the level 0 generators with the positive level generators are given by

$$[T^a{}_b, T^{cMN}] = \delta_b^c S^{aMN} + \delta_a^c S^{bMN}, \quad (A.5)$$

$$[T^a{}_b, T^{cd}{}_M] = 2\delta_b^{[c} S^{a|d]}{}_M + 2\delta_a^{[c} S^{b|d]}{}_M, \quad (A.6)$$

$$[T^a{}_b, T^{c_1 c_2 c_3 M}] = 3\delta_b^{[c_1} S^{a|c_2 c_3]}{}_M + 3\delta_a^{[c_1} S^{b|c_2 c_3]}{}_M, \quad (A.7)$$

$$[T^M{}_N, T^{aPQ}] = 2\delta_N^{[P} S^{a|M|Q]} + 2\delta_M^{[P} S^{a|N|Q]} - \frac{4}{5}\delta_N^M S^{aPQ}, \quad (A.8)$$

$$[T^M{}_N, T^{ab}{}_P] = -\delta_P^M S^{ab}{}_N - \delta_P^N S^{ab}{}_M + \frac{2}{4}\delta_N^M S^{ab}{}_P, \quad (A.9)$$

$$[T^M{}_N, T^{a_1 a_2 a_3 P}] = \delta_N^P S^{a_1 a_2 a_3 M} + \delta_M^P S^{a_1 a_2 a_3 N} - \frac{2}{5}\delta_N^M S^{a_1 a_2 a_3 P}, \quad (A.10)$$

The commutators of the positive level generators are given by

$$[T^{aMN}, T^{bPQ}] = \varepsilon^{MNPQR} S^{ab}{}_R + \delta_b^a \delta_{[P}^{[M} S^{N]}{}_{Q]} + 2\delta_{PQ}^{MN} J^a{}_b, \quad (A.11)$$

$$[T^{aMN}, T^{b_1 b_2}_P] = \delta_P^{[M} S^{ab_1 b_2 N]} - \varepsilon^{MNPQR} \delta_a^{[b_1} S^{b_2]QR} , \quad (A.12)$$

$$[T^{aMN}, T^{b_1 b_2 b_3}_P] = -12 \delta_a^{[b_1} \delta_{[M}^P S^{b_2 b_3]N]} , \quad (A.13)$$

$$[T^{a_1 a_2}_M, T^{b_1 b_2}_N] = -\frac{1}{2} \delta_{b_1 b_2}^{a_1 a_2} S^M{}_N - 4 \delta_N^M \delta_{[b_1}^{[a_1} J^{a_2]}_{b_2]} , \quad (A.14)$$

$$[T^{a_1 a_2}_M, T^{b_1 b_2 b_3}_N] = 12 \delta_{a_1 a_2}^{[b_1 b_2} S^{b_3]MN} , \quad (A.15)$$

$$[T^{a_1 a_2 a_3}_M, T^{b_1 b_2 b_3}_N] = -4! \delta_{b_1 b_2 b_3}^{a_1 a_2 a_3} S^M{}_N - 2 \cdot (3!)^2 \delta_N^M \delta_{[b_1 b_2}^{[a_1 a_2} J^{a_3]}_{b_3]} . \quad (A.16)$$

We next give the commutators with those of the generators of the vector representation. At level 0, we find

$$[T^a{}_b, P_c] = -\delta_c^a P_b - \delta_c^b P_a + \delta_b^a P_c , \quad (A.17)$$

$$[T^a{}_b, Z^{MN}] = \delta_b^a Z^{MN} , \quad (A.18)$$

$$[T^a{}_b, Z^c{}_M] = \delta_b^c Z^a{}_M + \delta_a^c Z^b{}_M + \delta_b^a Z^c{}_M , \quad (A.19)$$

$$[T^a{}_b, Z^{a_1 a_2}_M] = 2 \delta_b^{[a_1} Z^{a]a_2]M} + 2 \delta_a^{[a_1} Z^{b]a_2]M} + \delta_b^a Z^{a_1 a_2}_M , \quad (A.20)$$

$$[T^M{}_N, P_a] = 0 , \quad (A.21)$$

$$[T^M{}_N, Z^{PQ}] = 2 \delta_N^{[P} Z^{M]Q]} + 2 \delta_M^{[P} Z^{N]Q]} - \frac{4}{5} \delta_N^M Z^{PQ} , \quad (A.22)$$

$$[T^M{}_N, Z^a{}_P] = -\delta_P^M Z^a{}_N - \delta_P^N Z^a{}_M + \frac{2}{5} \delta_N^M Z^a{}_P , \quad (A.23)$$

$$[T^M{}_N, Z^{a_1 a_2}_P] = \delta_N^P Z^{a_1 a_2}_M + \delta_M^P Z^{a_1 a_2}_N - \frac{2}{5} \delta_N^M Z^{a_1 a_2}_P . \quad (A.24)$$

The commutators of the level 1 generators with the  $l_1$  representation are

$$[T^{aMN}, P_b] = \delta_b^a Z^{MN} , \quad (A.25)$$

$$[T^{aMN}, Z^{PQ}] = -\varepsilon^{MNPQR} Z^a{}_R + 2 \delta_{MN}^{PQ} P_a , \quad (A.26)$$

$$[T^{aMN}, Z^b{}_P] = 2 \delta_P^{[M} Z^{abN]} - \frac{1}{2} \delta_b^a \varepsilon_{MNPQR} Z^{QR} , \quad (A.27)$$

$$[T^{aMN}, Z^{b_1 b_2}_P] = -4 \delta_{[M}^P \delta_a^{[b_1} Z^{b_2]N]} . \quad (A.28)$$

Then the commutators of the level 2 generators with the  $l_1$  representation are

$$[T^{a_1 a_2}_M, P_b] = 2 \delta_b^{[a_1} Z^{a_2]}_M , \quad (A.29)$$

$$[T^{a_1 a_2}_M, Z^{NP}] = 2 \delta_M^{[N} Z^{a_1 a_2]P]} , \quad (A.30)$$

$$[T^{a_1 a_2}_M, Z^b{}_N] = -2 \delta_N^M \delta_{[a_1}^b Z^{a_2]}_N , \quad (A.31)$$

$$[T^{a_1 a_2}{}_M, Z^{b_1 b_2 N}] = 2\delta_{a_1 a_2}^{b_1 b_2} Z^{MN} . \quad (A.32)$$

Finally, the commutators of the level 3 generators with the  $l_1$  representation are

$$[T^{a_1 a_2 a_3 M}, P_b] = -6\delta_b^{[a_1} Z^{a_2 a_3]M} , \quad (A.33)$$

$$[T^{a_1 a_2 a_3 M}, Z^N{}_P] = 0 , \quad (A.34)$$

$$[T^{a_1 a_2 a_3 M}, Z^b{}_N] = 0 , \quad (A.35)$$

$$[T^{a_1 a_2 a_3 M}, Z^{b_1 b_2 N}] = 12\delta_M^N \delta_{[a_1 a_2}^{b_1 b_2} P_{a_3]} . \quad (A.36)$$

Finally we give the commutators of the even generators, that is,  $I_c(E_{11})$  with the odd generators. At level zero we have

$$[J^a{}_b, T^c{}_d] = \delta_b^c T^a{}_d + \delta_d^b T^c{}_a - \delta_a^c T^b{}_d - \delta_d^a T^c{}_b , \quad (A.37)$$

$$[J^a{}_b, T^M{}_N] = 0 , \quad (A.38)$$

$$[S^M{}_N, T^c{}_d] = 0 , \quad (A.39)$$

$$[S^M{}_N, T^P{}_Q] = \delta_N^P T^M{}_Q + \delta_Q^N T^P{}_M - \delta_M^P T^N{}_Q - \delta_Q^M T^P{}_N . \quad (A.40)$$

The level 0 even with odd generators are given by

$$[J^a{}_b, T^{cMN}] = \delta_b^c T^{aMN} - \delta_a^c T^{bMN} , \quad (A.41)$$

$$[J^a{}_b, T^{cd}{}_M] = 2\delta_b^{[c} T^{a|d]}{}_M - 2\delta_a^{[c} T^{b|d]}{}_M , \quad (A.42)$$

$$[J^a{}_b, T^{c_1 c_2 c_3 M}] = 3\delta_b^{[c_1} T^{a|c_2 c_3]M} - 3\delta_a^{[c_1} T^{b|c_2 c_3]M} , \quad (A.43)$$

$$[S^M{}_N, T^{aPQ}] = 2\delta_N^P T^{a|M|Q} - 2\delta_M^P T^{a|N|Q} , \quad (A.44)$$

$$[S^M{}_N, T^{ab}{}_P] = -\delta_P^M T^{ab}{}_N + \delta_P^N T^{ab}{}_M , \quad (A.35)$$

$$[S^M{}_N, T^{a_1 a_2 a_3 P}] = \delta_N^P T^{a_1 a_2 a_3 M} - \delta_M^P T^{a_1 a_2 a_3 N} , \quad (A.46)$$

and the level 1 even generators with the odd generators

$$[S^{aMN}, T^b{}_c] = -\delta_c^a T^{bMN} - \delta_b^a T^{cMN} , \quad (A.47)$$

$$[S^{aMN}, T^P{}_Q] = -2\delta_Q^M T^{a|P|N} - 2\delta_P^M T^{a|Q|N} , \quad (A.48)$$

$$[S^{aMN}, T^{bPQ}] = \varepsilon^{MNPQR} T^{ab}{}_R + \delta_b^a \delta_{[P}^M T^{N]}{}_Q + 2\delta_{PQ}^{MN} T^a{}_b - \frac{2}{5}\delta_{PQ}^{MN} \delta_b^a T^c{}_c , \quad (A.49)$$

$$[S^{aMN}, T^{b_1 b_2}{}_P] = \delta_P^M T^{ab_1 b_2 N} + \varepsilon^{MNPQR} \delta_a^{[b_1} T^{b_2]QR} , \quad (A.50)$$

$$[S^{aMN}, T^{b_1 b_2 b_3 P}] = 12\delta_a^{[b_1} \delta_{[M}^P T^{b_2 b_3]N]} . \quad (A.51)$$

Level 2 even generators with the odd generators are

$$[S^{a_1 a_2}_M, T^b_c] = -2\delta_c^{[a_1} T^{b|a_2]}_M - 2\delta_b^{[a_1} T^{c|a_2]}_M, \quad (A.52)$$

$$[S^{a_1 a_2}_M, T^N_P] = -\delta_M^N T^{a_1 a_2}_P - \delta_M^P T^{a_1 a_2}_N + \frac{2}{5}\delta_P^N T^{a_1 a_2}_M, \quad (A.53)$$

$$[S^{a_1 a_2}_M, T^{bNP}] = -\delta_M^N T^{ba_1 a_2 P} + \varepsilon_{MNPQR} \delta_b^{[a_1} T^{a_2]QR}, \quad (A.54)$$

$$[S^{a_1 a_2}_M, T^{b_1 b_2}_N] = -\frac{1}{2}\delta_{b_1 b_2}^{a_1 a_2} T^M_N - 4\delta_N^M \delta_{[b_1}^{[a_1} T^{a_2]}_{b_2]} + \frac{4}{5}\delta_M^N \delta_{b_1 b_2}^{a_1 a_2} T^c_c, \quad (A.45)$$

$$[S^{a_1 a_2}_M, T^{b_1 b_2 b_3 N}] = -12\delta_{a_1 a_2}^{[b_1 b_2} T^{b_3]MN}. \quad (A.56)$$

Finally, the level 3 even generators with the odd generators are

$$[S^{a_1 a_2 a_3 M}, T^b_c] = -\delta_c^{[a_1} T^{b|a_2 a_3]M} - \delta_b^{[a_1} T^{c|a_2 a_3]M}, \quad (A.57)$$

$$[S^{a_1 a_2 a_3 M}, T^N_P] = -\delta_P^M T^{a_1 a_2 a_3 N} - \delta_N^M T^{a_1 a_2 a_3 P} - \frac{2}{5}\delta_P^N T^{a_1 a_2 a_3 M}, \quad (A.48)$$

$$[S^{a_1 a_2 a_3 M}, T^{bNP}] = 12\delta_b^{[a_1} \delta_{[N}^M T^{a_2 a_3]}_{P]}, \quad (A.59)$$

$$[S^{a_1 a_2 a_3 M}, T^{b_1 b_2}_N] = -12\delta_{b_1 b_2}^{[a_1 a_2} T^{a_3]MN}, \quad (A.60)$$

$$[S^{a_1 a_2 a_3 M}, T^{b_1 b_2 b_3 N}] = -4!\delta_{b_1 b_2 b_3}^{a_1 a_2 a_3} T^M_N - 2 \cdot (3!)^2 \delta_N^M \delta_{[b_1 b_2}^{[a_1 a_2} T^{a_3]}_{b_3]} + \frac{2}{5} \cdot (3!) \delta_N^M \delta_{b_1 b_2 b_3}^{a_1 a_2 a_3} T^c_c. \quad (A.61)$$

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